

## 8

### Referências bibliográficas

ANDREWS, D. W. K.; LEE, I.; PLOBERGER, W. Optimal Changepoint Tests for Normal Linear Regression, **Journal of Econometrics**, v. 70, p.9-38, jan.1996.

APARISI, F. Hotelling's  $T^2$  control chart with adaptive sample sizes. **International Journal of Production Research**, v.34, n.10, p.2853–2862, out.1996.

APARISI, F.; HARO, C.L. Hotelling's  $T^2$  control chart with sampling intervals. **International Journal of Production Research**, v.39, n.14, p.3127–3140, mar.2001.

APARISI, F.; HARO, C.L. A comparison of  $T^2$  control charts with variable sampling schemes as opposed to NEWMA chart. **International Journal of Production Research**, v.41, n.10, p.2169–2182, 2003.

APARISI, F.; FUENTES, P.; DEL RIO, J. Gráficos de control multivariantes para el seguimiento de la contaminación litoral. **Ingeniería Industrial**, v.44, n.1, p.35–42, abr.2003.

BENNEYAN, J.C. Use and interpretation of statistical quality control charts. **International Journal for Quality in Health Care**, v.10, n.1, p.69-73, 1998.

BENNEYAN, J.C. Number-between g-type statistical control charts for monitoring adverse events. **Health Care Management Science**, v.4, p.305-318, 2001a.

BENNEYAN, J.C. Performance of number-between g-type statistical control charts for monitoring adverse events. **Health Care Management Science**, v.4, p.319-336, 2001b.

BRILL, R. V. A case study for control charting a product quality measure that is a continuous function over time, Presentation at the 45th Annual Fall Technical Conference, Toronto, Ontario, 2001.

BURNETT, L.; CHESHER, D. Application of CQI tools to the reduction of risk in needle stick injury. **Infection Control and Hospital Epidemiology**, v.16, n.9, p.503–505, 1995.

CHEN, Y.; HSIEH, K. Hotelling's  $T^2$  charts with variable sample size and control limit. **European Journal of Operational Research**, v.182, n.3, p.1251–1262, nov.2007.

COSTA, A.F.B.  $\bar{X}$  charts with variable sampling size. **Journal of Quality Technology**, v.26, p.155–163, jul.1994.

COSTA, A.F.B.  $\bar{X}$  charts with variable sample size and sampling intervals. **Journal of Quality Technology**, v.29, p.197-204, abr.1997.

COSTA, A.F.B. Joint  $\bar{X}$  and R Charts with Variable Sample Sizes and Sampling Intervals. **Journal of Quality Technology**, v.31, n.4, p.387-397, out.1999.

CROARKIN, C.; VARNER, R. **Measurement Assurance for Dimensional Measurements on Integrated-Circuit Photomasks**, NBS Technical Note 1164, U.S. Department of Commerce, Washington, DC, 1982.

CROSBY, P. **Quality is Free**. New York: Mentor/New American Library, 1979.

CURRAN, E.T; BENNEYAN, J.C.; HOOD, J. Controlling methicillin-resistant Staphylococcus aureus: A feedback approach using annotated statistical process control charts. **Infection Control and Hospital Epidemiology**, v.3, p.13–8, 2002.

ÇINLAR, E. **Introduction to Stochastic Process**. Englewood Cliffs, New York: Prentice Hall, 1975.

DING Y., ZENG L., ZHOU S. Phase I analysis for monitoring nonlinear profiles in manufacturing processes. **Journal of Quality Technology**, v.38, n.3, p.119-216, jul.2006.

DE MAGALHÃES, M.S.; COSTA, A.F.B; EPPRECHT, E.K . Constrained Optimization Model for the Design of an Adaptive X-bar Chart. **International Journal of Production Research**, v.40, n.13, p.3199-3218, 2002.

DE MAGALHÃES, M.S.; COSTA, A.F.B.; NETO, F. D. M. A hierarchy of adaptative  $\bar{X}$  control charts. **International Journal of Production Economics**, v.119, p-271-283, jun.2009.

DEMING, W.E. **Out of crisis**. Cambridge: MIT Press, 2000.

FARAZ, A.; MOGHADAM, M.B. Hotelling's  $T^2$  control chart with two adaptive sample sizes. **Quality and Quantity**, v.43, n.6, p.903–912, nov.2009.

FEIGENBAUM, A.V. **Total quality control**. 4.ed. New York: McGraw-Hill, 1961.

JENSEN, W.A.; BIRCH, J.B.; WOODALL W.H. Monitoring correlation within linear profiles using mixed models. **Journal of Quality Technology**, v.40, n.2, p.167-183, abr.2008.

JENSEN, W.A.; BIRCH, J.B. Profile monitoring via nonlinear mixed models. **Journal of Quality Technology**, v.41, n.1, p.18-34, jan. 2009.

JOHNSON, N.L.; KOTZ, S. **Distributions in Statistics**. New York: Wiley, 1969.

JURAN, J.M.; GODFREY, A.B. **Juran's quality handbook**. 5<sup>th</sup>ed. New York: McGraw-Hill, 1999.

KANG, L.; ALBIN, S.L. On-line monitoring when the process yields a linear profile. **Journal of Quality Technology**, v.32, n.4, p.418-42, out.2000.

KAZEMZADEH, R.B.; NOOROSSANA, R.; AMIRI, A. Monitoring polynomial profiles in quality control applications. **The International Journal of Advanced Manufacturing Technology**, v.42, n.7-8, jun. 2009.

KIM, K.; MAHMOUD, M. A.; WOODALL, W. H. On the monitoring of linear profiles. **Journal of Quality Technology**, v.35, n.3, p.317-328, jul.2003.

LIN, Y.; CHOU, C. On the design of variable sample size and sampling intervals  $\bar{X}$  charts under non-normality. **International Journal of Production Economics**, v.96, n.2, p-249-261, mai.2005.

LUCAS, J. M. Combined Shewhart - CUSUM quality control schemes. **Journal of Quality Technology**, v.14, p.51–59, ago.1982.

LUCAS, J. M.; SACCUCCI, M. S. Exponentially weighted moving average control schemes: properties and enhancements. **Technometrics**, v.32, p.1-29, fev.1990.

MAHMOUD, M. A. Phase I analysis of multiple linear regression profiles. **Communications in Statistics – Simulation and Computation**, v.37, n.4, p.2106-2130, 2008.

MAHMOUD, M. A; WOODALL, W. H. Phase I analysis of linear profiles with calibration applications. **Technometrics**, v.46, n.4, p.377-391, nov.2004.

MARTI, J.A; ANGUS, A.T. Multivariate control charts for ecological and environmental monitoring. **Ecological Applications**, v.14, n.6, p.1921-1935, 2004.

MESTECK, O.; PAVLIK, J.; SUCHANEK, M. Multivariate control charts: control charts for calibration curves. **Fresenius' Journal of analytical chemistry**, v.350, p.344-351, 1994.

MONTGOMERY, D.C. **Introduction to Statistical Quality Control**. 4<sup>th</sup>ed., John Wiley, 2001.

MONTGOMERY, D.C.; RUNGER, G.C. **Applied Statistics and Probability for Engineers**, 2<sup>th</sup>ed., Wiley, New York, 1999.

JURAN, J.M.; GODFREY, A.B. **Juran's quality handbook**. 5<sup>th</sup>ed. New York: McGraw-Hill, 1999.

PARKER, P.A.; FINLEY, T.D. Advancements in aircraft model force and attitude instrumentation by integrating statistical methods. **Journal of Aircraft**, v.44, n.2, p.436-443, 2007.

PRABHU, S.S.; RUNGER, G.C.; Keats, J.B.  $\bar{X}$  chart with adaptive sample sizes. **International Journal of Production Research**, v.31, n.12, p.2895-2909, dez.1993.

PRABHU, S.S.; MONTGOMERY, D. C.; RUNGER, G. C. A combined adaptive sample size and sampling interval X control scheme. **Journal of Quality Technology**, v.26, p.164-176, jul.1994.

REYNOLDS JR.; Marion R.; AMIN, R. W.; ARNOLD, J.C.; NACHLAS, J. A.  $\bar{X}$  charts with variable sampling intervals. **Technometrics**, v.30, p.181- 192, mai.1988.

SELLICK, J.A. The use of statistical process control charts in hospital epidemiology. **Infection Control and Hospital Epidemiology**, v.14, n.11, p.649-656, 1993.

SHERIFF, D. Diagnostic Procedures Facilitate the Solving of Gas Flow Problems, **Solid State Technology**, v.38. n.8, p.63-69, 1995.

STAUDHAMMER, C.; MANESS, T.C.; KOZAK, R.A. Profile charts for monitoring lumber manufacturing using laser range sensor data. **Journal of Quality Technology**, v.39, n.3, p.224-240, jul.2007.

STOVER, F. S.; BRILL, R.V. Statistical quality control applied to ion chromatography calibrations. **Journal of Chromatography A**, v.804, p.37-43, 1988.

STRANG, G. **Linear Algebra and its Applications**, Harcourt Brace Jovanovich College Publishers, Orlando, 1988.

TAGUCHI, G. **Introduction to quality engineering: designing quality into products and processes**. Tokio: Asian Productivity Organization, 1986.

WALKER E.; WRIGHT S.P. Comparing curves using additive models. **Journal of Quality Technology**, v.34, n.1, p.118-129, jan.2002.

WILLIAMS, J.D.; WOODALL W.H.; BIRCH, J.B. Statistical monitoring of nonlinear product and process quality profiles. **Quality and Reliability Engineering International**, v.23, n.7, p.925-941, 2007a.

WILLIAMS, J.D.; BIRCH, J.B.; WOODALL, W.H.; FERRY, N. M. Statistical monitoring of heteroscedastic dose-response profiles from high-throughput screening. **Journal of Agricultural, Biological and Environmental Statistics**, v.12, n.2, p.216-235, 2007b.

WOODALL, W.H.; SPITZNER, D.J.; MONTGOMERY, D.C.; GUPTA, S. Using control charts to monitor process and product quality profile. **Jornal of Quality Technology**, v.36, n.3, p.309-320, jul.2004.

YOUNG, T.M; WINISTORFER, P.M; WANG, S. Multivariate control charts of MDF and OSB vertical density profile attributes. **Forest Products Journal**, v.49, p.79-86, 1999.

ZIMMER, L.S.; MONTGOMERY, D.C.; RUNGER, G.C. Evaluation of a three-state adaptive sample size  $\bar{X}$  control chart. **International Journal of Production Research**, v.36, n.3, p.733-743, mar.1998.

## 9 Apêndices

Neste apêndice são apresentadas as três rotinas em R utilizadas na dissertação.

A primeira rotina, usada no capítulo 5, executa o cálculo do número médio de amostras até um sinal (*NMA*) e do número médio de itens a serem inspecionados até um sinal (*E(N)*) para os gráficos de controle  $\chi^2$  com PF e com TAV quando ocorrem deslocamentos em  $\beta_*^0$  e/ou  $\beta_*^1$ .

```
NMA_PF_TAV = function(n0,n1,n2)
{
  mat1=diag(2)
  vet1=cbind(c(1,1))
  vet2=cbind(c(n1,n2))
  amostra1= rep(0,n1)
  for(j in 1:n1)
  {
    amostra1[j] = j*(10/(n1+1))
  }
  xbarra1= mean (amostra1)
  sxx1=0
  s1=0
  for(j in 1:n1)
  {
    s1= (amostra1[j]-xbarra1)^2
    sxx1=sxx1+s1
  }
  amostra0= rep(0,n0)
  for(i in 1:n0)
  {
    amostra0[i] = i*(10/(n0+1))
  }
  xbarra0= mean (amostra0)
  sxx0=0
  s0=0
  for(i in 1:n0)
  {
    s0= (amostra0[i]-xbarra0)^2
    sxx0=sxx0+s0
  }
  amostra2= rep(0,n2)
  for(y in 1:n2)
  {
    amostra2[y] = y*(10/(n2+1))
  }
}
```

```

}
xbarra2= mean (amostra2)
sxx2=0
s2=0
for(y in 1:n2)
{
s2= (amostra2[y]-xbarra2)^2
sxx2=sxx2+s2
}
p0= (n0-n2)/(n1-n2)
delta0=0
delta1=0
resposta= matrix(0,8,121)
aux=0
for(i in 1:11)
{
for(k in 1:11)
{
resposta[6,aux+k]=qchisq(p0,2)
par_centralidade0 = n0* (delta0+ delta1*xbarra0)^2 + (delta1^2)*sxx0
par_centralidade1 = n1* (delta0+ delta1*xbarra1)^2 + (delta1^2)*sxx1
par_centralidade2 = n2* (delta0+ delta1*xbarra2)^2 + (delta1^2)*sxx2
vet=(c(p0,1-p0))
ele11=pchisq(resposta[6,aux+k],2, par_centralidade1)
ele21=pchisq(resposta[6,aux+k],2, par_centralidade2)
ele12=pchisq(10.597,2, par_centralidade1)- pchisq(resposta[6,aux+k],2,
par_centralidade1)
ele22=pchisq(10.597,2, par_centralidade2)- pchisq(resposta[6,aux+k],2,
par_centralidade2)
matprinc= rbind(c(ele11,ele12),c(ele21,ele22))
matmeio=solve(mat1-matprinc)
resposta[1,aux+k]=vet%%matmeio%%vet1
t=pchisq(10.597,2, par_centralidade0)
resposta[2,aux+k]=1/(1-t)
resposta[3,aux+k]=delta0
resposta[4,aux+k]=delta1
resposta[5,aux+k]= p0
resposta[7,aux+k]= vet%%matmeio%%vet2
resposta[8,aux+k]= n0*(1/(1-t))
delta0=delta0+0.2
}
aux = aux +11
delta1=delta1+0.025
delta0 =0
}
return (resposta)
}

```

A segunda rotina, usada no capítulo 5, executa o cálculo do número médio de amostras até um sinal ( $NMA$ ) e do número médio de itens a serem inspecionados até um sinal ( $E(N)$ ) para os gráficos de controle  $\chi^2$  com PF e com TAV quando ocorrem deslocamentos em  $\sigma_*$ .

```

NMA_PF_TAV = function(n0,n1,n2)
{
mat1=diag(2)
vet1=cbind(c(1,1))
vet2=cbind(c(n1,n2))
amostra1= rep(0,n1)
for(j in 1:n1)
{
amostra1[j] = j*(10/(n1+1))
}
xbarra1= mean (amostra1)
sxx1=0
s1=0
for(j in 1:n1)
{
s1= (amostra1[j]-xbarra1)^2
sxx1=sxx1+s1
}
amostra0= rep(0,n0)
for(i in 1:n0)
{
amostra0[i] = i*(10/(n0+1))
}
xbarra0= mean (amostra0)
sxx0=0
s0=0
for(i in 1:n0)
{
s0= (amostra0[i]-xbarra0)^2
sxx0=sxx0+s0
}
amostra2= rep(0,n2)
for(y in 1:n2)
{
amostra2[y] = y*(10/(n2+1))
}
xbarra2= mean (amostra2)
sxx2=0
s2=0
for(y in 1:n2)
{
s2= (amostra2[y]-xbarra2)^2
sxx2=sxx2+s2
}
p0= (n0-n2)/(n1-n2)
delta0=0
delta1=0
gama=1
resposta= matrix(0,7,11)

```

```

for(k in 1:11)
{
resposta[5,k]=qchisq(p0,2)
par_centralidade0 = 1/(gama^2)* (n0* (delta0+ delta1*xbarra0)^2 +
(delta1^2)*sxx0)
par_centralidade1 = 1/(gama^2)* (n1* (delta0+ delta1*xbarra1)^2 +
(delta1^2)*sxx1)
par_centralidade2 = 1/(gama^2)* (n2* (delta0+ delta1*xbarra2)^2 +
(delta1^2)*sxx2 )
vet=(c(p0, 1-p0))
ele11=pchisq(resposta[5,k] /(gama^2),2, par_centralidade1)
ele21=pchisq(resposta[5,k] /(gama^2),2, par_centralidade2)
ele12=pchisq(10.597/(gama^2),2, par_centralidade1)- pchisq(resposta[5,k]
/(gama^2),2, par_centralidade1)
ele22=pchisq(10.597/(gama^2),2, par_centralidade2)- pchisq(resposta[5,k]
/(gama^2),2, par_centralidade2)
matprinc= rbind(c(ele11,ele12),c(ele21,ele22))
matmeio=solve(mat1-matprinc)
resposta[1,k]=vet%*%matmeio%*%vet1
t=pchisq(10.597/(gama^2),2, par_centralidade0)
resposta[2,k]=1/(1-t)
resposta[3,k]=gama
resposta[4,k]= p0
resposta[6,k]= vet%*%matmeio%*%vet2
resposta[7,k]= n0*(1/(1-t))
gama=gama+0.2
}
return (resposta)
}

```



A terceira rotina, usada no capítulo 6, refere-se à análise de sensibilidade do gráfico com TAV. Através desta rotina são obtidos valores do *NMA*, para valores variados de  $n_2$  quando ocorrem deslocamentos em  $\beta_*^0$  e  $\beta_*^1$ .

```

NMA_PF_TAV = function(n0,n1)
{
mat1=diag(2)
vet1=cbind(c(1,1))
amostra1= rep(0,n1)
for(j in 1:n1)
{
amostra1[j] = j*(10/(n1+1))
}
xbarra1= mean (amostra1)
sxx1=0
s1=0
for(j in 1:n1)
{
s1= (amostra1[j]-xbarra1)^2
sxx1=sxx1+s1
}
delta0=0.2
delta1=0.025
resposta= matrix(0,100,28)
col=0
lin=3
n2=n0+1
while (n2<=100)
{
amostra2= rep(0,n2)
for(y in 1:n2)
{
amostra2[y] = y*(10/(n2+1))
}
xbarra2= mean (amostra2)
sxx2=0
s2=0
for(y in 1:n2)
{
s2= (amostra2[y]-xbarra2)^2
sxx2=sxx2+s2
}
p0= (n0-n2)/(n1-n2)
for(i in 1:5)
{
for(k in 1:5)
{
resposta[lin,3]=qchisq(p0,2)
par_centralidade1 = n1* (delta0+ delta1*xbarra1)^2 + (delta1^2)*sxx1
par_centralidade2 = n2* (delta0+ delta1*xbarra2)^2 + (delta1^2)*sxx2
vet=(c(p0,1-p0))
ele1=pchisq(resposta[lin,3],2, par_centralidade1)
ele2=pchisq(resposta[lin,3],2, par_centralidade2)
}
}
}
}

```

```
ele12=pchisq(10.597,2, par_centralidade1)- pchisq(resposta[lin,3],2,
par_centralidade1)
ele22=pchisq(10.597,2, par_centralidade2)- pchisq(resposta[lin,3],2,
par_centralidade2)
matprinc= rbind(c(ele11,ele12),c(ele21,ele22))
matmeio=solve(mat1-matprinc)
resposta[lin, 4+ col]=vet%*%matmeio%*%vet1
resposta[1,4+ col]=delta0
resposta[2,4+ col]=delta1
resposta[lin,2]= p0
resposta[lin,1]= n2
delta0=delta0+0.2
col = col +1
}
delta1=delta1+0.025
delta0 =0.2
}
n2=n2+1
lin=lin+1
col=0
delta1=0.025
}
return (resposta)
}
```



```

ele11=pchisq(resposta[lin,3]/(gama^2),2, par_centralidade1)
ele21=pchisq(resposta[lin,3]/(gama^2),2, par_centralidade2)
ele12=pchisq(10.597/(gama^2),2, par_centralidade1)- pchisq(resposta[lin,3]/(gama^2),2,
par_centralidade1)
ele22=pchisq(10.597/(gama^2),2, par_centralidade2)- pchisq(resposta[lin,3]/(gama^2),2,
par_centralidade2)
matprinc= rbind(c(ele11,ele12),c(ele21,ele22))
matmeio=solve(mat1-matprinc)
resposta[lin, 4+ col]=vet%*%matmeio%*%vet1
resposta[1,4+ col]=delta0
resposta[2,4+ col]=delta1
resposta[3,4+ col]=gama
resposta[lin,2]= p0
resposta[lin,1]= n2
delta0=delta0+0.2
col = col +1
}
delta1=delta1+0.025
delta0 =0
}
delta1=0
delta0 =0
gama=gama+0.2
}
n2=n2+1
lin=lin+1
col=0
gama=1.2
}
return (resposta)
}

```