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A

Programa em Maple: Lindsted Poincaré modificado - vibração forçada

```
> restart;
Ordem da solução
> nt:=2;
nt := 2
```

A.1

Rotinas do método da perturbação

```
> solucao_aproximada_frequencia:=proc(pot1,pot2,epsilon)
> global eq,omega,omega0,_X,i,__omega;
> __omega:=0omega^pot1:
> for i from 1 to pot2 do
> __omega:=__omega-epsilon^i*_e[i];
> od;
> eq:=subs(omega0^pot1=__omega,eq);
> end proc:
> solucao_aproximada_tempo:=proc(pot,epsilon)
> global eq,tau,X,XX,__x,i;
> X:=0: XX:=0:
> for i from 0 to pot do
> X:=X+epsilon^i*__x[i](t);
> XX:=XX+epsilon^i*__x[i];
> od;
> eq:=subs(x(t)=X,eq);
> end proc:
```

```

> monta_equacoes:=proc(pot)
> global eq,_eq; local i,j,AA,eq1;
> eq1:=expand(eq):
> for i from pot by -1 to 1 do
> eq1:=subs((mu^i)=AA[i],eq1): _eq[i]:=diff(eq1,AA[i]);
AA[i]:=0;
> od;
> _eq[0]:=eq1;
> for i from 1 to pot do
> for j from 0 to i-1 do
> _eq[i]:=subs(_x[j](t)=xxx[j](t),_eq[i]);
> od:
> od:
> end proc:
> resolva:=proc(i)
> global _eq,_x,t;
> _x[i]:=rhs(dsolve(_eq[i],_x[i](t)));
> end proc:
> resolva_eqd:=proc(eq_,ivar_)
> global omega,t,_x,solu;
> local eq1,eq2,i,ii,AAAA,BBBB,D1,D2,solu1,op2;
> ii:=nops(op(1,eq_))-2;
> op2:=op(2,eq_);
> eq1:=subs({diff(_x[ivar_](t),t$2)=AAAA,_x[ivar_](t)=BBBB
> },op(1,eq_)):
> D2:=diff(eq1,AAAA);
> D1:=diff(eq1,BBBB);
> eq1:=subs({AAAA=0,BBBB=0},eq1)=op2:
> solu:=0:
> if(ii>1)then
> for i from 1 to ii do
> eq2:=D2*diff(_x[ivar_](t),'$(t,2))+D1*_x[ivar_](t)=
> -op(i,op(1,eq1));
> solu1:=rhs(dsolve(eq2,_x[ivar_](t)));
> if(i>1)then
> solu1:=subs(cat(_C,2*ind-1)=0,cat(_C,2*ind)=0,solu1);
> end if:
> solu:=solu+solu1;
> od;
> else
> eq2:=D2*diff(_x[ivar_](t),'$(t,2))+D1*_x[ivar_](t)=
> -op(1,eq1);
> rhs(dsolve(eq2,_x[ivar_](t)));
> solu:=solu+%;
> end if;
> solu;
> end proc:

```

Rotina para resolver equações diferenciais lineares com muitos termos não-homogeneos.

```

> resolva_eqd_old:=proc(eq_,ivar_)
> global Omega,t,__x,solu,ind,SIMPLIFY;
> local eq1,eq2,i,ii,CCC,DDD,v1,v2,solu1;
> eq1:=subs(diff(__x[ivar_](t),t$2)=CCC,op(1,eq_));
> v1:=diff(eq1,CCC);
> eq1:=subs(__x[ivar_](t)=DDD,eq1);
> v2:=diff(eq1,DDD);
> eq1:=subs(CCC=0,DDD=0,eq1);
> eq1:=SIMPLIFY(eq1);
> ii:=nops(eq1);
> solu:=0;
> if(ii>1)then
> for i from 1 to ii do
> eq2:=v1*diff(__x[ivar_](t),'$(t,2))+v2*__x[ivar_](t)=
- op(i,eq1);
> solu1:=rhs(dsolve(eq2,__x[ivar_](t)));
> if(i>1)then
> solu1:=subs(cat(_C,2*ind-1)=0,cat(_C,2*ind)=0,solu1);
> end if;
> solu:=solu+%;
> od;
> else
> eq2:=v1*diff(__x[ivar_](t),'$(t,2))+v2*__x[ivar_](t)=-eq1;
> rhs(dsolve(eq2,__x[ivar_](t)));
> solu:=solu+%;
> end if;
> solu;
> end proc:
> elimina_secular_term:=proc(i)
> global Omega,t,__x,_e; local AA,AAA;
> subs(Omega*t=AAA,__x[i]);
> diff(%,t);
> subs(sin(AAA)=AA,%); diff(%,AA);
> _e[i]:=rhs(isolate(simplify(%=0),_e[i]));
> end proc:
> aplica_condicoes_iniciais:=proc(eq_,icte)
> global __x,_C,t;
> t:=0;
> solve(eq_,cat('_C',icte));
> end proc:
> EXPANDE:=proc(eqq)
> subs({sin=SINN,cos=COSS},eqq);
> expand(%);
> subs({SINN=sin,COSS=cos},%);
> end proc:

```

A.2

Equação de Duffing

```

> printlevel:=2;

```

printlevel := 2

```
> eqd:=diff(x(t),t$2)+2*mu*zeta*omega0*diff(x(t),t)+
omega0^2*x(t)+alpha*x(t)^2+beta*x(t)^3=mu*F(t);
```

$$eqd := \left(\frac{d^2}{dt^2} x(t)\right) + 2\mu\zeta\omega_0\left(\frac{d}{dt} x(t)\right) + \omega_0^2 x(t) + \alpha x(t)^2 + \beta x(t)^3 = \mu F(t)$$

Analisando a não linearidade quadrática

```
> beta:=0; zeta:=0; eqd:=subs(F(t)=F*cos(Omega*t),eqd);
```

$$\beta := 0$$

$$\zeta := 0$$

$$eqd := \left(\frac{d^2}{dt^2} x(t)\right) + \omega_0^2 x(t) + \alpha x(t)^2 = \mu F \cos(\Omega t)$$

```
> eq:=eqd: mu:=alpha:
```

```
> solucao_aproximada_frequencia(2,nt,mu);
```

$$\left(\frac{d^2}{dt^2} x(t)\right) + (\Omega^2 - \alpha_{e_1} - \alpha^2_{e_2}) x(t) + \alpha x(t)^2 = \alpha F \cos(\Omega t)$$

Frequência da resposta - Ω .

```
> i:='i':
```

```
> Omega^2=omega0^2+sum(mu^i*_e[i], 'i'=1..nt);
```

```
> omega0^2=Omega^2-sum(mu^i*_e[i], 'i'=1..nt);
```

$$\Omega^2 = \omega_0^2 + \alpha_{e_1} + \alpha^2_{e_2}$$

$$\omega_0^2 = \Omega^2 - \alpha_{e_1} - \alpha^2_{e_2}$$

```
> eq:=expand(eq);
```

$$eq := \left(\frac{d^2}{dt^2} x(t)\right) + x(t) \Omega^2 - x(t) \alpha_{e_1} - x(t) \alpha^2_{e_2} + \alpha x(t)^2 = \alpha F \cos(\Omega t)$$

```
> solucao_aproximada_tempo(nt,mu);
```

$$\left(\frac{\partial^2}{\partial t^2} \%1\right) + \%1 \Omega^2 - \%1 \alpha_{e_1} - \%1 \alpha^2_{e_2} + \alpha \%1^2 = \alpha F \cos(\Omega t)$$

$$\%1 := _x_0(t) + \alpha _x_1(t) + \alpha^2 _x_2(t)$$

```
> eqd;
```

$$\left(\frac{d^2}{dt^2} x(t)\right) + \omega_0^2 x(t) + \alpha x(t)^2 = \alpha F \cos(\Omega t)$$

```
> X;
```

$$_x_0(t) + \alpha _x_1(t) + \alpha^2 _x_2(t)$$

```
> eq:=expand(eq):
```

```
> monta_equacoes(nt):
```

```
> for i from 0 to nt do
```

```
> _eq[i]; od;
```

$$\left(\frac{d^2}{dt^2} _x_0(t)\right) + \Omega^2 _x_0(t) = 0$$

$$\left(\frac{d^2}{dt^2} _x_1(t)\right) + \Omega^2 _x_1(t) - _e_1 xxx_0(t) + xxx_0(t)^2 = F \cos(\Omega t)$$

$$\left(\frac{d^2}{dt^2} _x_2(t)\right) + \Omega^2 _x_2(t) - _e_1 xxx_1(t) - _e_2 xxx_0(t)$$

$$+ 2 xxx_0(t) xxx_1(t) = 0$$

```
> eqd:
```

```
> subs(x(t)=X,eqd):
```

```
> auxaux:=collect(expand(%),mu):
```

```
> for i from 1 to nt do
```

```
> eqaux[i]:=subs(_x[i](t)=0,op(1,_eq[i]));
```

```
> eqaux[i]:=expand(eqaux[i])-op(2,_eq[i]);
```

```
> od:
```

A.2.1

Resolve as equações

```

> RETIRA_TERMOS_SECULARES:=proc()
> global __x,ind,t,_e,eq,eq1,eq2;
> local i,AAA,BBB,solu;
> eq:=__x[ind]:
> for i from 1 to 10*ind do
>   eq:=subs(sin(i*Omega*t)=AAA[i],eq);
>   eq:=subs(cos(i*Omega*t)=BBB[i],eq);
>   od:
>   solu[1]:=0: solu[2]:=0:
>   eq:=diff(eq,t);
>   #SENOS
>   eq1:=diff(eq,AAA[1]);
>   if(eq1<>0)then
>     solu[1]:=expand(solve(eq1=0,_e[ind]));
>   end if;
>   #COSSENOS
>   eq2:=diff(eq,BBB[1]);
>   if(eq2<>0)then
>     solu[2]:=expand(solve(eq2=0,_e[ind]));
>   end if;
>   _e[ind]:=solu[1];
>   if(expand(eq1)=0)then
>     if(expand(eq2)<>0)then
>       _e[ind]:=solu[2];
>     end if;
>   else
>     _e[ind]:=solu[2];
>   end if;
> end proc:
> unassign('_e'); unassign('__x');
> ind:=0;
> __x[ind]:=a*subs({mu=1,F=1},op(2,eqd));
> __v[ind]:=diff(__x[ind],t);

```

$$ind := 0$$

$$__x_0 := a \cos(\Omega t)$$

$$__v_0 := -a \sin(\Omega t) \Omega$$

```

> printlevel:=2;

```

```

> for ind from 1 to nt do
>   cat("EQUACAO ",ind);
>   cat("SIMPLIFICANDO A EQUACAO ",ind);
>   eq:=expand(eqaux[ind]);
>   eq:=subs({seq(xxx[j](t)=_x[j],j=0..ind-1)},eq);
>   _eq[ind]:=diff(_x[ind](t),t$2)+Omega^2*_x[ind](t)+
EXPANDE(combine(e
>   q,trig))=0;
>   "RESOLVENDO A EQUACAO";
>   _x[ind]:=resolva_eqd(_eq[ind],ind);
>   "IMPONDO AS CONDICÕES INICIAIS";
>   _x[ind]:=subs({_C1=0,_C2=0},_x[ind]);
>   cat("SIMPLIFICANDO A SOLUCAO ",ind);
>   _x[ind]:=collect(EXPANDE(_x[ind]),{sin,cos});
>   _v[ind]:=diff(_x[ind],t);
>   "RETIRANDO OS TERMOS SECULARES";
>   RETIRA_TERMOS_SECULARES();
>   _x[ind]:=EXPANDE(_x[ind]);
>   od;

```

printlevel := 2

“EQUACAO 1”

“SIMPLIFICANDO A EQUACAO 1”

$$eq := -_e_1 xxx_0(t) + xxx_0(t)^2 - F \cos(\Omega t)$$

$$eq := -_e_1 a \cos(\Omega t) + a^2 \cos(\Omega t)^2 - F \cos(\Omega t)$$

$$\begin{aligned} _eq_1 &:= \left(\frac{d^2}{dt^2} _x_1(t) \right) + \Omega^2 _x_1(t) - _e_1 a \cos(\Omega t) + \frac{1}{2} a^2 \cos(2 \Omega t) \\ &+ \frac{a^2}{2} - F \cos(\Omega t) = 0 \end{aligned}$$

“RESOLVENDO A EQUACAO”

$$\begin{aligned} _x_1 &:= \sin(\Omega t) _C2 + \cos(\Omega t) _C1 + \frac{1}{2} \frac{ _e_1 a (\cos(\Omega t) + \sin(\Omega t) \Omega t)}{\Omega^2} \\ &+ \frac{1}{6} \frac{ a^2 \cos(2 \Omega t)}{\Omega^2} - \frac{a^2}{2 \Omega^2} + \frac{1}{2} \frac{ F (\cos(\Omega t) + \sin(\Omega t) \Omega t)}{\Omega^2} \end{aligned}$$

“IMPONDO AS CONDICÕES INICIAIS”

$$\begin{aligned} _x_1 &:= \frac{1}{2} \frac{ _e_1 a (\cos(\Omega t) + \sin(\Omega t) \Omega t)}{\Omega^2} + \frac{1}{6} \frac{ a^2 \cos(2 \Omega t)}{\Omega^2} - \frac{a^2}{2 \Omega^2} \\ &+ \frac{1}{2} \frac{ F (\cos(\Omega t) + \sin(\Omega t) \Omega t)}{\Omega^2} \end{aligned}$$

“SIMPLIFICANDO A SOLUCAO 1”

$$\begin{aligned} _x_1 &:= \left(\frac{1}{2} \frac{ _e_1 a t}{\Omega} + \frac{F t}{2 \Omega} \right) \sin(\Omega t) + \left(\frac{1}{2} \frac{ _e_1 a}{\Omega^2} + \frac{F}{2 \Omega^2} \right) \cos(\Omega t) \\ &+ \frac{1}{6} \frac{ a^2 \cos(2 \Omega t)}{\Omega^2} - \frac{a^2}{2 \Omega^2} \end{aligned}$$

$$\begin{aligned} _ _ v_1 := & \left(\frac{1}{2} \frac{e_1 a}{\Omega} + \frac{F}{2\Omega} \right) \sin(\Omega t) + \left(\frac{1}{2} \frac{e_1 a t}{\Omega} + \frac{F t}{2\Omega} \right) \cos(\Omega t) \Omega \\ & - \left(\frac{1}{2} \frac{e_1 a}{\Omega^2} + \frac{F}{2\Omega^2} \right) \sin(\Omega t) \Omega - \frac{1}{3} \frac{a^2 \sin(2\Omega t)}{\Omega} \end{aligned}$$

“RETIRANDO OS TERMOS SECULARES”

$$_ _ x_1 := \frac{1}{6} \frac{a^2 \cos(2\Omega t)}{\Omega^2} - \frac{a^2}{2\Omega^2}$$

“EQUACAO 2”

“SIMPLIFICANDO A EQUACAO 2”

$$eq := \frac{F _ _ x_1(t)}{a} - _ e_2 _ _ x_0(t) + 2 _ _ x_0(t) _ _ x_1(t)$$

$$eq := \frac{F \left(\frac{1}{6} \frac{a^2 \cos(2\Omega t)}{\Omega^2} - \frac{a^2}{2\Omega^2} \right)}{a} - _ e_2 a \cos(\Omega t)$$

$$+ 2 a \cos(\Omega t) \left(\frac{1}{6} \frac{a^2 \cos(2\Omega t)}{\Omega^2} - \frac{a^2}{2\Omega^2} \right)$$

$$_ eq_2 := \left(\frac{d^2}{dt^2} _ _ x_2(t) \right) + \Omega^2 _ _ x_2(t) + \frac{1}{6} \frac{F a \cos(2\Omega t)}{\Omega^2} - \frac{F a}{2\Omega^2}$$

$$- _ e_2 a \cos(\Omega t) - \frac{5}{6} \frac{a^3 \cos(\Omega t)}{\Omega^2} + \frac{1}{6} \frac{a^3 \cos(3\Omega t)}{\Omega^2} = 0$$

“RESOLVENDO A EQUACAO”

$$\begin{aligned} _ _ x_2 := & 5 \sin(\Omega t) _ C2 + 5 \cos(\Omega t) _ C1 + \frac{1}{18} \frac{F a \cos(2\Omega t)}{\Omega^4} + \frac{F a}{2\Omega^4} \\ & + \frac{1}{2} \frac{e_2 a (\cos(\Omega t) + \sin(\Omega t) \Omega t)}{\Omega^2} + \frac{5}{12} \frac{a^3 (\cos(\Omega t) + \sin(\Omega t) \Omega t)}{\Omega^4} \\ & + \frac{1}{48} \frac{a^3 \cos(3\Omega t)}{\Omega^4} \end{aligned}$$

“IMPONDO AS CONDICAOES INICIAIS”

$$\begin{aligned} _ _ x_2 := & \frac{1}{18} \frac{F a \cos(2\Omega t)}{\Omega^4} + \frac{F a}{2\Omega^4} + \frac{1}{2} \frac{e_2 a (\cos(\Omega t) + \sin(\Omega t) \Omega t)}{\Omega^2} \\ & + \frac{5}{12} \frac{a^3 (\cos(\Omega t) + \sin(\Omega t) \Omega t)}{\Omega^4} + \frac{1}{48} \frac{a^3 \cos(3\Omega t)}{\Omega^4} \end{aligned}$$

“SIMPLIFICANDO A SOLUCAO 2”

$$\begin{aligned} _ _ x_2 := & \left(\frac{1}{2} \frac{e_2 a t}{\Omega} + \frac{5 a^3 t}{12 \Omega^3} \right) \sin(\Omega t) + \left(\frac{1}{2} \frac{e_2 a}{\Omega^2} + \frac{5 a^3}{12 \Omega^4} \right) \cos(\Omega t) \\ & + \frac{1}{18} \frac{F a \cos(2\Omega t)}{\Omega^4} + \frac{F a}{2\Omega^4} + \frac{1}{48} \frac{a^3 \cos(3\Omega t)}{\Omega^4} \end{aligned}$$

$$\begin{aligned} _ _ v_2 := & \left(\frac{1}{2} \frac{e_2 a}{\Omega} + \frac{5 a^3}{12 \Omega^3} \right) \sin(\Omega t) + \left(\frac{1}{2} \frac{e_2 a t}{\Omega} + \frac{5 a^3 t}{12 \Omega^3} \right) \cos(\Omega t) \Omega \\ & - \left(\frac{1}{2} \frac{e_2 a}{\Omega^2} + \frac{5 a^3}{12 \Omega^4} \right) \sin(\Omega t) \Omega - \frac{1}{9} \frac{F a \sin(2\Omega t)}{\Omega^3} - \frac{1}{16} \frac{a^3 \sin(3\Omega t)}{\Omega^3} \end{aligned}$$

“RETIRANDO OS TERMOS SECULARES”

$$--x_2 := \frac{1}{18} \frac{F a \cos(2 \Omega t)}{\Omega^4} + \frac{F a}{2 \Omega^4} + \frac{1}{48} \frac{a^3 \cos(3 \Omega t)}{\Omega^4}$$

A.2.2

Relação frequência-deslocamento

```
> for i from 1 to nt do
>   _e[i]; j:='j':
>   __eq[i]:=omega0^2+sum(mu^j*_e[j], 'j'=1..i)-0mega^2;
>   V[i]:=__eq[i]:
>   H[i]:=diff(V[i], omega);
> od:
> for i from 1 to nt do
>   __eq[i];
> od;
```

$$\omega_0^2 - \frac{\alpha F}{a} - \Omega^2$$

$$\omega_0^2 - \frac{\alpha F}{a} - \frac{5 \alpha^2 a^2}{6 \Omega^2} - \Omega^2$$

```
> unassign('0mega');
> for i from 1 to nt do isolate(__eq[i], 0mega^2); od;
```

$$\Omega^2 = \omega_0^2 - \frac{\alpha F}{a}$$

$$\Omega^2 = \omega_0^2 - \frac{\alpha F}{a} - \frac{5 \alpha^2 a^2}{6 \Omega^2}$$

A.2.3

Soluções

```
> v0:=0; omega0:='omega0':
> for i from 1 to nt do
>   j:='j':
>   __eq[i]:=omega0+sum(mu^j*_e[j], 'j'=1..i)-0mega;
>   __X[i]:=sum(mu^j*__x[j], 'j'=0..i);
> od;
```

$$v_0 := 0$$

$$j := j$$

$$--eq_1 := \omega_0 - \frac{\alpha F}{a} - \Omega$$

$$--X_1 := a \cos(\Omega t) + \alpha \left(\frac{1}{6} \frac{a^2 \cos(2 \Omega t)}{\Omega^2} - \frac{a^2}{2 \Omega^2} \right)$$

$$j := j$$

$$--eq_2 := \omega_0 - \frac{\alpha F}{a} - \frac{5 \alpha^2 a^2}{6 \Omega^2} - \Omega$$

$$\begin{aligned} _X_2 := & a \cos(\Omega t) + \alpha \left(\frac{1}{6} \frac{a^2 \cos(2 \Omega t)}{\Omega^2} - \frac{a^2}{2 \Omega^2} \right) \\ & + \alpha^2 \left(\frac{1}{18} \frac{F a \cos(2 \Omega t)}{\Omega^4} + \frac{F a}{2 \Omega^4} + \frac{1}{48} \frac{a^3 \cos(3 \Omega t)}{\Omega^4} \right) \end{aligned}$$

A.2.4

Curva de ressonância

```
> A:='A': Omega:='Omega': F:='F': F0:='F0':
> alpha:='alpha': omega0:='omega0':
> __eq[1];
```

$$\omega_0 - \frac{\alpha F}{a} - \Omega$$

```
> F0;
```

$$F_0$$

```
> F:=F0/mu; __eq[nt];
```

$$F := \frac{F_0}{\alpha}$$

$$\omega_0 - \frac{F_0}{a} - \frac{5 \alpha^2 a^2}{6 \Omega^2} - \Omega$$

```
> __X[1];
```

$$a \cos(\Omega t) + \alpha \left(\frac{1}{6} \frac{a^2 \cos(2 \Omega t)}{\Omega^2} - \frac{a^2}{2 \Omega^2} \right)$$

```
> with(Optimization);
> FindAmplitude:=proc(_a)
> global __x,a,mu,t,Omega,XXX;
> local i,T,max,min,dt;
> a:=_a; XXX:=0; max:=0;
> for i from 0 to nt do
> XXX:=XXX+mu^i*__x[i];
> od;
> T:=evalf(2*Pi/Omega);
> max:=Maximize(XXX,t=0..4*T)[1];
> min:=abs(Minimize(XXX,t=0..4*T)[1]);
> dt:=T/500;
> for t from 0 by dt to 4*T do
> if(abs(evalf(XXX))>max)then
> max:=evalf(XXX);
> end if;
> od;
> t:='t':
> if(max>min) then
> max;
> else
> min;
> end if;
> end proc;
```

```

[ImportMPS, Interactive, LPSolve, LSSolve, Maximize, Minimize,
NLPSolve, QPSolve]
> CurvaResonancia:=proc(vi,delta1,vf,parte)
> global __eq,nt,a,Amp,solu,Omega,d,cont,delta,fd,txt;
> local i,j,k,kk,init,RA2,RA3,aux1,soluu;
> Omega:=vi; delta:=delta1;
> txt:=sprintf("CurvaResonancia_F0=%2.3g_alpha=%2.3g_beta=
> %2.3g_omega0=%2.3g_OmegaxA_nt=%d.dat",
> F0,alpha,beta,omega0,nt);
> fd:=fopen(txt,WRITE,BINARY);
> fprintf(fd,"      Omega      a      Amp      a[1]
> a[2]\n");
> for i from 1 by 1 while Omega<= vf do
> a:='a':
> __eq[nt];
> if(omega0-Omega<>0)then
> soluu:=solve(__eq[nt],a);
> k:=nops([soluu]):
> if(k=1)then
> solu[1]:=soluu;
> else
> solu:=soluu;
> end if;
> for j from 1 to k do
> if(Im(solu[j])=0)then
> Amp:=FindAmplitude(Re(solu[j]));
> aux1:=subs({cos(Omega*t)=AAA,cos(2*Omega*t)=BBB,
> cos(3*Omega*t)=CCC},__X[nt]);
> RA2:=evalf(diff(aux1,BBB)/diff(aux1,AAA));
> RA3:=evalf(diff(aux1,CCC)/diff(aux1,AAA));
> fprintf(fd,"%7.4f %14.10f %14.10f %14.10f
> %14.10f\n",Omega,a,Amp,RA2,RA3);
> end if;
> od;
> end if;
> Omega:=Omega+delta;
> od;
> fclose(fd);
> end proc:
> __X[nt];

```

$$\begin{aligned}
 & a \cos(\Omega t) + \alpha \left(\frac{1}{6} \frac{a^2 \cos(2\Omega t)}{\Omega^2} - \frac{a^2}{2\Omega^2} \right) \\
 & + \alpha^2 \left(\frac{1}{18} \frac{F0 a \cos(2\Omega t)}{\alpha \Omega^4} + \frac{F0 a}{2\Omega^4 \alpha} + \frac{1}{48} \frac{a^3 \cos(3\Omega t)}{\Omega^4} \right)
 \end{aligned}$$

```
> F0:=1; omega0:=1; alpha:=1; F;
```

$$F0 := 1$$

$$\omega0 := 1$$

$$\alpha := 1$$

$$1$$

```
> __eq[1]; __eq[2];
```

```

1 - 1/a - Omega
1 - 1/a - 5*a^2/(6*Omega^2) - Omega

> t:='t':
> eqd;

      (d^2 x(t)) + x(t) + x(t)^2 = cos(Omega t)

> NT:=nt;
      NT := 2
> for i from 1 to NT do
>   nt:=i; a:='a': t:='t':
>   CurvaResonancia(0.01,0.01,2.0);
> od;

      nt := 1
      a := a
      t := t
      nt := 2
      a := a
      t := t

> t:='t': a:='a': Omega:='Omega';
> __X[1]; collect(__X[2],cos);
      Omega := Omega
      a cos(Omega t) + 1/6 * a^2 cos(2 Omega t) - a^2/(2 Omega^2)
a cos(Omega t) + (a^2/(6 Omega^2) + a/(18 Omega^4)) cos(2 Omega t) + a/(2 Omega^4) - a^2/(2 Omega^2) + 1/48 * a^3 cos(3 Omega t)
> __eq[1]; __eq[2];

1 - 1/a - Omega
1 - 1/a - 5*a^2/(6*Omega^2) - Omega

```

B

Programa em Maple: Método de Taylor - vibração livre

```
> restart;  
> with(linalg):
```

B.1

Solução

```
> eqd:=diff(u(t),t$2)+omega0^2*u(t)+alpha*u(t)^2+beta*u(t)^3=F(t);
```

$$eqd := \left(\frac{d^2}{dt^2} u(t)\right) + \omega_0^2 u(t) + \alpha u(t)^2 + \beta u(t)^3 = F(t)$$

```
> eqd:=subs({alpha=0,F(t)=0},eqd);
```

$$eqd := \left(\frac{d^2}{dt^2} u(t)\right) + \omega_0^2 u(t) + \beta u(t)^3 = 0$$

nt = maior potência da série + 1

```
> nt:=4+1;
```

$$nt := 5$$

```
> eqd;
```

$$\left(\frac{d^2}{dt^2} u(t)\right) + \omega_0^2 u(t) + \beta u(t)^3 = 0$$

```
> isolate(%,diff(u(t),'$(t,2)));
```

$$\frac{d^2}{dt^2} u(t) = -\omega_0^2 u(t) - \beta u(t)^3$$

```
> u2:=rhs(%);
```

$$u2 := -\omega_0^2 u(t) - \beta u(t)^3$$

```
> taylor(u(t),t=0,4);
```

$$u(0) + D(u)(0)t + \frac{1}{2}(D^{(2)})(u)(0)t^2 + \frac{1}{6}(D^{(3)})(u)(0)t^3 + O(t^4)$$

série de taylor

```
> i:='i': unassign('c');
```

```
> U:=sum(c[i]*t^i,i=0..nt-1);
```

$$U := c_0 + c_1 t + c_2 t^2 + c_3 t^3 + c_4 t^4$$

```
> dU:=diff(U,t);
```

$$dU := c_1 + 2c_2 t + 3c_3 t^2 + 4c_4 t^3$$

ausência de amortecimento

```
> v0:=0;
```

$$v_0 := 0$$

derivadas da série polinomial

```
> dt[0]:=U;
> for i from 1 to nt-1 do
>   dt[i]:=diff(dt[i-1],t);
> od:

      dt_0 := c_0 + c_1 t + c_2 t^2 + c_3 t^3 + c_4 t^4
> eq[0]:=u0; eq[1]:=v0; eq[2]:=u2;
> for i from 3 to nt-1 do
>   diff(eq[i-1],t):
>   eq[i]:=expand(subs(diff(u(t),'$(t,2))=eq[2],%));
> od:

      eq_0 := u0
      eq_1 := 0
      eq_2 := -omega^2 u(t) - beta u(t)^3
> for i from 0 to nt-1 do
>   EQ[i]:=expand(subs({diff(u(t),t)=v0,u(t)=u0},eq[i]));
> od:
coeficientes da série
> for i from 0 to nt-1 do
>   c[i]:=EQ[i]/i!;
> od:
> U;
> dU;
```

$$u0 + \left(-\frac{1}{2}\omega^2 u0 - \frac{1}{2}\beta u0^3\right)t^2 + \left(\frac{1}{24}\omega^4 u0 + \frac{1}{6}\omega^2 \beta u0^3 + \frac{1}{8}\beta^2 u0^5\right)t^4$$

$$2\left(-\frac{1}{2}\omega^2 u0 - \frac{1}{2}\beta u0^3\right)t + 4\left(\frac{1}{24}\omega^4 u0 + \frac{1}{6}\omega^2 \beta u0^3 + \frac{1}{8}\beta^2 u0^5\right)t^3$$

B.2

Relação frequência-amplitude

```
> omega:='omega':
> subs({t=T/4,v0=0},U)=0:
> EQ:=subs(T=2*Pi/omega,%):
> EQ:=expand(%/u0);
```

$$EQ := 1 - \frac{\pi^2 \omega^2}{8 \omega^2} - \frac{u0^2 \pi^2 \beta}{8 \omega^2} + \frac{\pi^4 \omega^4}{384 \omega^4} + \frac{u0^2 \pi^4 \omega^2 \beta}{96 \omega^4} + \frac{u0^4 \pi^4 \beta^2}{128 \omega^4} = 0$$

B.3

Exemplo

```
> u0:='u0': omega0:='omega0': omega:='omega': beta:='beta':
> b:='b':
> omega0:=1.2; beta:=0.0001; u0:=0.3;
```

$$\begin{aligned}\omega_0 &:= 1.2 \\ \beta &:= 0.0001 \\ u_0 &:= 0.3\end{aligned}$$

> U;

$$0.3 - 0.2160013500 t^2 + 0.02592064800 t^4$$

B.3.1

Verificação da solução: integração numérica

```
> eqd2:=y(t)=diff(x(t),t),diff(y(t),t)=-omega0^2*x(t)-beta*x(t)^3;
> init:=x(0)=u0,y(0)=v0;
```

$$eqd2 := y(t) = \frac{d}{dt} x(t), \frac{d}{dt} y(t) = -1.44 x(t) - 0.0001 x(t)^3$$

$$init := x(0) = 0.3, y(0) = 0$$

```
> f:=dsolve({eqd2,init},type=numeric,method=classical[rk4],
maxfun=999999,output=procedurelist):
```

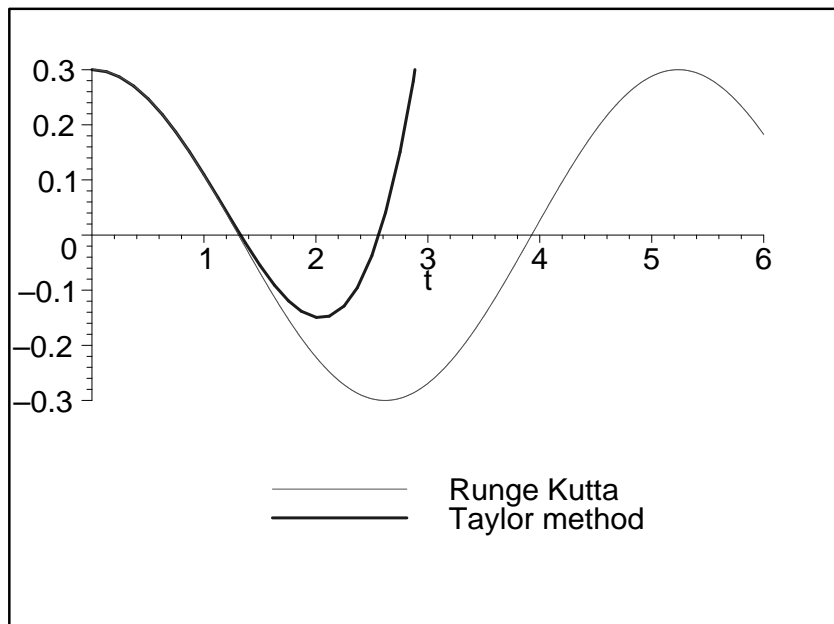
```
> vi:=0; vf:=6;
> #escrevendo na lista
> delta:=0.01: cont:=0:
> for k from vi by delta to vf do
>   cont:=cont+1;
>   od: cont;
>   d1:=array(1..cont,1..2): d2:=array(1..cont,1..2):
>   cont:=0:
>   for k from vi by delta to vf do
>     cont:=cont+1;
>     d1[cont,1]:=k;
>     d1[cont,2]:=eval(x(t),f(k));
>     d2[cont,1]:=k;
>     d2[cont,2]:=eval(y(t),f(k));
>   od:
>   d1g:=convert(d1,listlist):
>   d2g:=convert(d2,listlist):
```

$$vi := 0$$

$$vf := 6$$

601

```
> plot([d1g,U],t=0..vf,y=-u0..u0,color=[red,blue],thickness=
[2,4],legend=["Runge Kutta","Taylor method"]);
```



B.3.2

Transformação da solução em série de Taylor em uma série de Fourier

```
> printlevel:=1;
> unassign('a'); unassign('w');
> unassign('A'); unassign('_omega'); unassign('omega');
> omega0:='omega0': beta:='beta': delta:= 'delta':
> b:='b': u0:='u0':
```

printlevel := 1

número de harmônicos

```
> nh:=nops(U)-1;#(nt-1)/2;
> i:='i': omega:='omega':
> xx:=sum(A[i]*cos((2*i-1)*omega*t),i=1..nh);
```

nh := 2

$$xx := A_1 \cos(\omega t) + A_2 \cos(3\omega t)$$

série de cada harmônico

```
> a*cos(x*t);
> taylor(%,t,nt):
> serie:=convert(%,polynom):
```

$$a \cos(xt)$$

```
> serie2:=subs({seq((x^2)^i=x2^i,i=1..nt)},serie):
> EXPANDE:=proc(equacao)
> local k,i,soma:
> k:=nops(equacao);
> soma:=0:
> for i from 1 to k do
> soma:=soma+expand(op(i,equacao));
> od;
> soma;
> end proc:
```

substituição dos harmônicos na fórmula da série

```
> for i from 1 to nh do
>   for j from 1 to 1 do
>     expand(subs(x=(2*i-1)*omega,serie));
>     subs(a=A[i],%);
>     parte[i]:=%;
>   od;
>   cat("harmonico ",i),"ok";
> od;
> UHBM:=0:
> for i from 1 to nh do
>   UHBM:=UHBM+collect(parte[i],t);
> od;
> UHBM:=collect(UHBM,t):
>
>   "harmonico 1", "ok"
>   "harmonico 2", "ok"
>
> xx;
```

$$A_1 \cos(\omega t) + A_2 \cos(3\omega t)$$

primeiras equações

```
> p0:=subs(t=0,U):
> p1:=subs(t=0,UHBM):
> eq[1]:=p0;
> eqhbm[1]:=p1;
```

$$eq_1 := u0$$

$$eqhbm_1 := A_1 + A_2$$

demais equações

```
> cont:=1:
> for j from 2 by 2 to nt-1 do
>   if(cont>nh)then break; end if;
>   for k from 1 by 1 to 1 do
>     cont:=cont+1:
>     subs({seq(t^i=0,i=2..j-2),seq(t^i=0,i=j+1..2*nt)},U)-p0:
>     eq[cont]:=subs(t=1,%);
>     subs({seq(t^i=0,i=2..j-2),seq(t^i=0,i=j+1..nt)},UHBM)-p1:
>     eqhbm[cont]:=subs(t=1,%);
>   od;
>   t^j,cat("equacao ",cont),"ok";
> od;
```

$$t^2, \text{ "equacao 2", "ok"}$$

$$t^4, \text{ "equacao 3", "ok"}$$

```
> neq:=cont;
```

$$neq := 3$$

Determinação das constantes

```
> eq[1]-eqhbm[1]=0;
> A[1]:=solve(%,A[1]);
```

$$u0 - A_1 - A_2 = 0$$


```


$$A_1 := u0 - A_2$$

> expand(eq[2]-eqhbm[2]=0);

$$-\frac{\omega^2 u0}{2} - \frac{\beta u0^3}{2} + \frac{\omega^2 u0}{2} + 4 A_2 \omega^2 = 0$$

> M:=Matrix(nh-1): V:=Matrix(1..nh-1,1):
> for i from 2 to nh do
>   cont:=1:
>   for j from 2 by 1 to nh do
>     M[i-1,cont]:=diff(expand(eq[i]-eqhbm[i]),A[j]);
>     cont:=cont+1:
>   od:
>   V[i-1,1]:=-subs({seq(A[jj]=0,jj=2..nh)},expand(eq[i]-eqhbm[i]));
>   od:
> M;

$$\begin{bmatrix} 4\omega^2 \end{bmatrix}$$

> V;

$$\begin{bmatrix} \frac{\omega^2 u0}{2} + \frac{\beta u0^3}{2} - \frac{\omega^2 u0}{2} \end{bmatrix}$$

> R:=evalm(inverse(M)&*V):
> for i from 2 to nh do
>   A[i]:=R[i-1,1];
> od:

frequência da resposta
> _eq:=expand(eq[nh+1]-eqhbm[nh+1]):
> omega0:=1.2; beta:=0.0001; u0:=0.3;

$$\omega_0 := 1.2$$


$$\beta := 0.0001$$


$$u_0 := 0.3$$

> aux:=fsolve(_eq,omega);

$$aux := -1.200002812, -0.4000040625, 0.4000040625, 1.200002812$$

> aux[4];

$$1.200002812$$

> omega:=%;

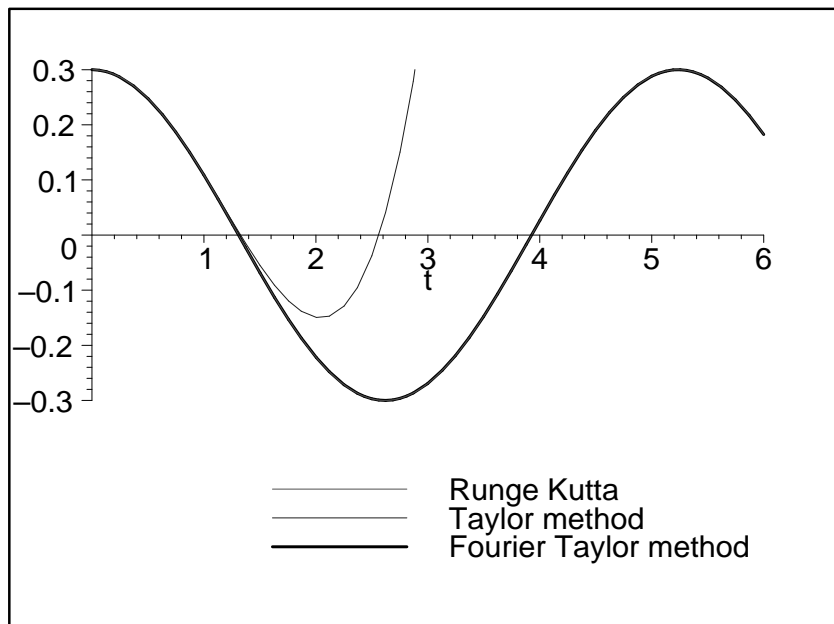
$$\omega := 1.200002812$$

> i:='i':
> xxx:=sum(A[i]*cos((2*i-1)*omega*t),i=1..nh);

$$xxx := 0.2999999414 \cos(1.200002812 t) + 0.5861083642 \cdot 10^{-7} \cos(3.600008436 t)$$

> plot([d1g,U,xxx],t=0..vf,y=-u0..u0,color=[red,blue,black],
thickness=[2,2,4],legend=["Runge Kutta","Taylor method",
"Fourier Taylormethod"]);

```



```
> u0:='u0': omega0:='omega0':
> omega:='omega': beta:='beta':
```

B.4

Transformação da solução em série de Taylor em uma solução de Lindstedt-Poincaré

```
> printlevel:=1;
> unassign('a'); unassign('w');
> unassign('A'); unassign('_omega'); unassign('omega');
> omega0:='omega0': beta:='beta': delta:= 'delta': u0:='u0':
```

printlevel := 1

```
> collect(U,{beta,t});
```

$$u0 + \left(-\frac{1}{2}\omega0^2 u0 - \frac{1}{2}\beta u0^3\right)t^2 + \left(\frac{1}{24}\omega0^4 u0 + \frac{1}{6}\omega0^2 \beta u0^3 + \frac{1}{8}\beta^2 u0^5\right)t^4$$

```
> nops(%);
```

3

aproximação até β será correta

máxima potência em beta - se for número de termos-1 faltará uma equação

```
> pb:=%-2;
```

número de harmônicos

```
> nh:=pb+1; i:='i': omega:='omega':
```

retirada das potências de beta que não podem ser representadas corretamente pela solução de LP

```
> Ucopy:=subs({seq(beta^i=0,i=pb+1..10*pb)},U):
```

```
> xx:=sum(A[i]*cos((2*i-1)*omega*t),i=1..nh);
```

```

                                pb := 1
                                nh := 2
                                xx := A1 cos(ω t) + A2 cos(3 ω t)
> xx2:=xx: ni:=0: j:='j':
> for i from 1 to nh do
> ni:=ni+(pb-(i-1)+1);
> xx2:=subs(A[i]=sum(a[i,j]*beta^j,j=i-1..pb),xx2);
> A[i]:=sum(a[i,j]*beta^j,j=i-1..pb);
> _omega[i]:=(2*i-1)*omega;
> od;
> xx2;
                                (a1,0 + a1,1 β) cos(ω t) + a2,1 β cos(3 ω t)
> ni;
                                3
> j:='j':
> "número de incógnitas";
> ni:=ni+pb+1;
> xx2:=subs({omega=sum(w[j]*beta^j,j=0..pb)},xx2);
> omega:=sum(w[j]*beta^j,j=0..pb);
                                "número de incógnitas"
                                ni := 5
                                xx2 := (a1,0 + a1,1 β) cos((w0 + w1 β) t) + a2,1 β cos(3 (w0 + w1 β) t)
                                ω := w0 + w1 β
> unassign('a'); unassign('w');
série de cada harmônico
> a*cos(x*t);
> taylor(%,t,nt);
> serie:=convert(%,polynom);
                                a cos(x t)
                                a -  $\frac{a x^2}{2} t^2 + \frac{a x^4}{24} t^4 + O(t^5)$ 
                                serie := a -  $\frac{1}{2} a x^2 t^2 + \frac{1}{24} a x^4 t^4$ 
> serie2:=subs({seq((x^2)^i=x2^i,i=1..nt)},serie);
                                serie2 := a -  $\frac{1}{2} a x^2 t^2 + \frac{1}{24} a x^2 t^4$ 
> _omega[2];
                                3 w0 + 3 w1 β
> pb;
                                1
> EXPANDE:=proc(equacao)
> local k,i,soma:
> k:=nops(equacao);
> soma:=0:
> for i from 1 to k do
> soma:=soma+expand(op(i,equacao));
> od;
> soma;
> end proc:

```

```

> expand(_omega[2]^2);

$$9 w_0^2 + 18 w_0 w_1 \beta + 9 w_1^2 \beta^2$$

> subs({seq(beta^i=0,i=pb+1..10*pb)},%);

$$9 w_0^2 + 18 w_0 w_1 \beta$$

substituição dos harmônicos na fórmula da série
> ULP:=0:
> for i from 1 to nh do
> for j from 1 to 1 do
> #expandindo omega^2
> expand(_omega[i]^2):
> #retirando as potencias em beta que nao interessam
> subs({seq(beta^i=0,i=pb+1..10*pb)},%);
> #substituindo o omega^2 com as potencias em beta que
interessam
> expand(subs(x2=%,serie2));
> #retirando as novas potencias em beta que nao interessam
> subs({seq(beta^i=0,i=pb+1..10*pb)},%);
> #inserindo a amplitude do harmonico
> subs(a=A[i],%);
> #retirando as novas potencias em beta que nao interessam
> parte[i]:=subs({seq(beta^i=0,i=pb+1..10*pb)},expand(%));
> od;
> cat("harmonico ",i),"made";
> od;
> ULP:=0:
> for i from 1 to nh do
> ULP:=ULP+collect(parte[i],t);
> od;
> ULP:=collect(ULP,t):
"harmonico 1", "made"
"harmonico 2", "made"
> sort(subs({seq(beta^i=0,i=pb+1..10*pb)},ULP),t,ascending);


$$a_{1,1} \beta + a_{2,1} \beta + a_{1,0} + \left(-\frac{1}{2} w_0^2 a_{1,0} - \frac{1}{2} w_0^2 a_{1,1} \beta - w_0 w_1 \beta a_{1,0} - \frac{9}{2} a_{2,1} \beta w_0^2\right) t^2 + \left(\frac{1}{24} w_0^4 a_{1,0} + \frac{1}{24} w_0^4 a_{1,1} \beta + \frac{1}{6} w_0^3 w_1 \beta a_{1,0} + \frac{27}{8} a_{2,1} \beta w_0^4\right) t^4$$

primeiras equações
> p0:=subs(t=0,Ucopy):
> p1:=subs(t=0,ULP):
> eq[1]:=p0;
> eqlp[1]:=p1;


$$eq_1 := u0$$


$$eqlp_1 := a_{2,1} \beta + a_{1,0} + a_{1,1} \beta$$

número de incógnitas
> ni;
```

demais equações

```

> cont:=1:
> for j from 2 by 2 to nt-1 do
>   for k from 1 by 1 to 1 do
>     cont:=cont+1:
>     subs({seq(t^i=0,i=2..j-2),seq(t^i=0,i=j+1..2*nt)}),
Ucopy)-p0:
>     eq[cont]:=subs(t=1,%);
>     subs({seq(t^i=0,i=2..j-2),seq(t^i=0,i=j+1..nt)}),ULP)-p1:
>     eqlp[cont]:=subs(t=1,%);
>     od:
>     t^j,cat("equacao ",cont),"ok";
>     od;

t^2, "equacao 2", "ok"
t^4, "equacao 3", "ok"

> neq:=cont:

```

B.4.1

Determinação das constantes

```

> unassign('a'); unassign('w');
> i:='i':
> a[1,0]:=u0: w[0]:=omega0:
> printlevel:=1;
> for k from 1 to neq do
>   cat("EQUACAO ",k);
>   for KKK from 1 to 1 do
>     variaveis:=1:
>     p0:=subs(beta=0,eq[k]):
>     p1:=subs(beta=0,eqlp[k]):
>     #potencia beta^0
>     if(expand(p0-p1)<>0)then
>       if(k=1)then
>         isolate(p0=p1,a[k,0]);
>         a[k,k-1]:=expand(rhs(%));
>         variaveis:=variaveis,sprintf("a[%d,%d]",k,k-1);
>       else
>         isolate(p0=p1,w[k-2]);
>         w[k-2]:=expand(rhs(%));
>         variaveis:=variaveis,sprintf("w[%d]",k-2);
>       end if;
>     end if;
>     #potencia beta^j
>     for j from 1 to pb do
>       aux1:=subs(subs({seq(beta^i=0,i=j+1..pb),beta^j=AAA},
eq[k]))-p0:
>       aux2:=subs(subs({seq(beta^i=0,i=j+1..pb),beta^j=AAA},
eqlp[k]))-p1:
>       if(subs({AAA=1,beta=0},expand(aux1-aux2))<>0)then
>         subs({AAA=1,beta=0},aux1=aux2);
>         if(j+1<k)then
>           isolate(%,w[j]);
>           w[j]:=expand(rhs(%));
>           variaveis:=variaveis,sprintf("w[%d]",j);
>         else

```

```
> isolate(%,a[k,j]);
> a[k,j]:=expand(rhs(%));
> variaveis:=variaveis,sprintf("a[%d,%d]",k,j);
> end if;
> end if;
> od;
> od;
> "found",variaveis;
> od;
```

```
printlevel := 1
"EQUACAO 1"
"found", 1, "a[1,1]"
"EQUACAO 2"
"found", 1, "a[2,1]"
"EQUACAO 3"
"found", 1, "w[1]"
```

```
> xx2;
```

```
(u0 -  $\frac{u0^3 \beta}{32 \omega 0^2}$ ) cos(( $\omega 0 + \frac{3 u0^2 \beta}{8 \omega 0}$ ) t) +  $\frac{1}{32} \frac{u0^3 \beta \cos(3 (\omega 0 + \frac{3 u0^2 \beta}{8 \omega 0}) t)}{\omega 0^2}$ 
> omega;
```

$$\omega 0 + \frac{3 u0^2 \beta}{8 \omega 0}$$

solução de primeira ordem obtida com LP tradicional

```
> omega0+3/8*beta/omega0*x0^2-21/256*beta^2/omega0^3*x0^4
+81/2048*beta^3/omega0^5*x0^6;
```

$$\omega 0 + \frac{3 \beta x0^2}{8 \omega 0} - \frac{21 \beta^2 x0^4}{256 \omega 0^3} + \frac{81 \beta^3 x0^6}{2048 \omega 0^5}$$

```
> xx2;
```

```
(u0 -  $\frac{u0^3 \beta}{32 \omega 0^2}$ ) cos(( $\omega 0 + \frac{3 u0^2 \beta}{8 \omega 0}$ ) t) +  $\frac{1}{32} \frac{u0^3 \beta \cos(3 (\omega 0 + \frac{3 u0^2 \beta}{8 \omega 0}) t)}{\omega 0^2}$ 
> U;
```

$$u0 + (-\frac{1}{2} \omega 0^2 u0 - \frac{1}{2} \beta u0^3) t^2 + (\frac{1}{24} \omega 0^4 u0 + \frac{1}{6} \omega 0^2 \beta u0^3 + \frac{1}{8} \beta^2 u0^5) t^4$$

```
> sprintf("%d termos = %d harmonicos",nops(U),pb+1);
```

```
"3 termos = 2 harmonicos"
```

C

Programa em Maple: Fourier-Taylor - vibração forçada amortecida

```
> restart;
> with(linalg):
```

C.1

Solução

```
> eqd:=diff(u(t),t$2)+2*zeta*omega0*diff(u(t),t)+omega0^2*u(t)
+alpha*u(t)^2+beta*u(t)^3=F(t);
```

$$eqd := \left(\frac{d^2}{dt^2} u(t) \right) + 2 \zeta \omega_0 \left(\frac{d}{dt} u(t) \right) + \omega_0^2 u(t) + \alpha u(t)^2 + \beta u(t)^3 = F(t)$$

```
> eqd:=subs({alpha=0,F(t)=F*cos(0mega*t)},eqd);
```

$$eqd := \left(\frac{d^2}{dt^2} u(t) \right) + 2 \zeta \omega_0 \left(\frac{d}{dt} u(t) \right) + \omega_0^2 u(t) + \beta u(t)^3 = F \cos(\Omega t)$$

```
> nt:=7;
```

$$nt := 7$$

```
> eqd;
```

$$\left(\frac{d^2}{dt^2} u(t) \right) + 2 \zeta \omega_0 \left(\frac{d}{dt} u(t) \right) + \omega_0^2 u(t) + \beta u(t)^3 = F \cos(\Omega t)$$

```
> isolate(%,diff(u(t),'$'(t,2)));
```

$$\frac{d^2}{dt^2} u(t) = F \cos(\Omega t) - 2 \zeta \omega_0 \left(\frac{d}{dt} u(t) \right) - \omega_0^2 u(t) - \beta u(t)^3$$

```
> u2:=rhs(%);
```

$$u2 := F \cos(\Omega t) - 2 \zeta \omega_0 \left(\frac{d}{dt} u(t) \right) - \omega_0^2 u(t) - \beta u(t)^3$$

```
> diff(u2,t$2);
```

$$\begin{aligned} & -F \cos(\Omega t) \Omega^2 - 2 \zeta \omega_0 \left(\frac{d^3}{dt^3} u(t) \right) - \omega_0^2 \left(\frac{d^2}{dt^2} u(t) \right) - 6 \beta u(t) \left(\frac{d}{dt} u(t) \right)^2 \\ & - 3 \beta u(t)^2 \left(\frac{d^2}{dt^2} u(t) \right) \end{aligned}$$

```
> c[0]:=u0;
```

```
> c[1]:=v0;
```

```
> c[2]:=u2;
```

```
> for i from 3 to nt do
```

```
> c[i]:=diff(c[i-1],t);
```

```
> od:
```

$$c_0 := u_0$$

$$c_1 := v_0$$

```


$$c_2 := F \cos(\Omega t) - 2\zeta \omega_0 \left(\frac{d}{dt} u(t)\right) - \omega_0^2 u(t) - \beta u(t)^3$$

> c0[0]:=u0;
> c0[1]:=v0;
> c0[2]:=subs({u(t)=u0,diff(u(t),t)=v0,
> cos(Omega*t+phi)=cos(phi),sin(Omega*t+phi)=sin(phi),
> cos(Omega*t)=1,sin(Omega*t)=0},u2);

$$c0_0 := u0$$


$$c0_1 := v0$$


$$c0_2 := F - 2\zeta \omega_0 v0 - \omega_0^2 u0 - \beta u0^3$$

> for i from 3 to nt do
> c0[i]:=expand(subs({u(t)=u0,diff(u(t),t)=v0,
> cos(Omega*t+phi)=cos(phi),sin(Omega*t+phi)=sin(phi),
> cos(Omega*t)=1,sin(Omega*t)=0,seq(diff(u(t),'$(t,j))=
du[j](u0,v0,Omega),j=2..i-1)},c[i]));
> od:
série de taylor
> i:='i':
> U:=sum(c0[i]*t^i/i!,i=0..nt-1):

```

C.1.1

Transforma a solução em série de Taylor em uma série de Fourier

```

> printlevel:=1:
> unassign('a'); unassign('w');
> unassign('A'); unassign('B'); unassign('_omega');
> unassign('omega'); unassign('Omega');
> omega0:='omega0': beta:='beta': delta:= 'delta': F:='F':
zeta:='zeta':
> F0:='F0':
> b:='b': u0:='u0': phi:='phi': v0:='v0':
> nops(U)-2: (%-1)/2: round(%-.01):
número de harmônicos
> nh:='%';
> i:='i': omega:='omega':
> xx:=sum(A[i]*cos((2*i-1)*Omega*t)+B[i]*sin((2*i-1)*Omega*t)
,i=1..nh);

$$nh := 2$$


$$xx := A_1 \cos(\Omega t) + B_1 \sin(\Omega t) + A_2 \cos(3 \Omega t) + B_2 \sin(3 \Omega t)$$

> a*cos(x*t);
> taylor(%,t,nt):
> serie:=convert(%,polynom):

$$a \cos(x t)$$

> serie2:=subs({seq((x^2)^i=x2^i,i=1..nt)},serie):
> b*sin(x*t);
> taylor(%,t,nt):
> serie_s:=convert(%,polynom):

$$b \sin(x t)$$

> serie2_s:=subs({seq((x^3)^i=x3^i,i=1..nt)},serie_s):

```



```

> EXPANDE:=proc(equacao)
> local k,i,soma:
> k:=nops(equacao);
> soma:=0:
> for i from 1 to k do
> soma:=soma+expand(op(i,equacao));
> od;
> soma;
> end proc:
> for i from 1 to nh do
> for j from 1 to 1 do
> expand(subs(x=(2*i-1)*Omega,serie));
> subs(a=A[i],%);
> parte[i]:=%;
> expand(subs(x=(2*i-1)*Omega,serie_s));
> subs(b=B[i],%);
> parte[i]:=parte[i]+%;
> od;
> cat("harmonico ",i),"ok";
> od;
> UHBM:=0:
> for i from 1 to nh do
> UHBM:=UHBM+collect(parte[i],t);
> od:
> UHBM:=collect(UHBM,t):
                                "harmonico 1", "ok"
                                "harmonico 2", "ok"

> xx;
       $A_1 \cos(\Omega t) + B_1 \sin(\Omega t) + A_2 \cos(3 \Omega t) + B_2 \sin(3 \Omega t)$ 
primeiras equações
> p0:=subs(t=0,U):
> p1:=subs(t=0,UHBM):
> eq[1]:=p0;
> eqhbm[1]:=p1;
                                 $eq_1 := u0$ 
                                 $eqhbm_1 := A_1 + A_2$ 

demais equações
> cont:=1:
> for j from 1 by 1 to nt do
> if(cont>2*nh+1)then break; end if;
> for k from 1 by 1 to 1 do
> cont:=cont+1:
> subs({seq(t^i=0,i=j+1..nt),t^j=1},U)-p0:
> eq[cont]:=subs(t=0,%);
> subs({seq(t^i=0,i=j+1..nt),t^j=1},UHBM)-p1:
> eqhbm[cont]:=subs(t=0,%);
> od:
> t^j,cat("equacao ",cont),"ok";
> od;
                                t, "equacao 2", "ok"
                                t^2, "equacao 3", "ok"
                                t^3, "equacao 4", "ok"

```

```

t4, "equacao 5", "ok"
t5, "equacao 6", "ok"

> neq:=cont;
                                neq := 6
> for i from 1 to 5 do
> eq[i]=eqhbm[i];
> od;

                                u0 = A1 + A2
                                v0 = B1 Ω + 3 B2 Ω
                                
$$\frac{F}{2} - \zeta \omega_0 v_0 - \frac{\omega_0^2 u_0}{2} - \frac{\beta u_0^3}{2} = -\frac{1}{2} A_1 \Omega^2 - \frac{9}{2} A_2 \Omega^2$$

                                
$$-\frac{1}{3} \zeta \omega_0 du_2(u_0, v_0, \Omega) - \frac{\omega_0^2 v_0}{6} - \frac{\beta u_0^2 v_0}{2} = -\frac{1}{6} B_1 \Omega^3 - \frac{9}{2} B_2 \Omega^3$$

                                
$$-\frac{F \Omega^2}{24} - \frac{1}{12} \zeta \omega_0 du_3(u_0, v_0, \Omega) - \frac{1}{24} \omega_0^2 du_2(u_0, v_0, \Omega) - \frac{\beta u_0 v_0^2}{4}$$

                                
$$-\frac{1}{8} \beta u_0^2 du_2(u_0, v_0, \Omega) = \frac{1}{24} A_1 \Omega^4 + \frac{27}{8} A_2 \Omega^4$$

> xx2:=subs({seq(A[i]=cc[i](u0,v0,0mega),i=0..nh),
> seq(B[i]=dd[i](u0,v0,0mega),i=1..nh)},xx);

                                xx2 := cc1(u0, v0, Ω) cos(Ω t) + dd1(u0, v0, Ω) sin(Ω t)
                                + cc2(u0, v0, Ω) cos(3 Ω t) + dd2(u0, v0, Ω) sin(3 Ω t)

```

Determinação das amplitudes

```

> nh;
                                2
> nops(xx);
                                4
> neq;
                                6
> M:=Matrix(2*nh): V:=Matrix(1..2*nh,1):
> for i from 1 to neq-2 do
> cont:=1:
> for j from 1 by 1 to nh do
> M[i,cont]:=diff(expand(eq[i]-eqhbm[i]),B[j]);
> cont:=cont+1:
> M[i,cont]:=diff(expand(eq[i]-eqhbm[i]),A[j]);
> cont:=cont+1:
> od:
> V[i,1]:=-subs({seq(A[jj]=0,jj=0..nh),
> seq(B[jj]=0,jj=1..nh)},expand(eq[i]-eqhbm[i]));
> od:
> cont;
                                5
> M;

```

$$\begin{bmatrix} 0 & -1 & 0 & -1 \\ -\Omega & 0 & -3\Omega & 0 \\ 0 & \frac{\Omega^2}{2} & 0 & \frac{9\Omega^2}{2} \\ \frac{\Omega^3}{6} & 0 & \frac{9\Omega^3}{2} & 0 \end{bmatrix}$$

```

> R:=evalm(inverse(M)&*V):
> cont:=1:
> for i from 1 by 2 to 2*nh do
> B[cont]:=R[i,1];
> A[cont]:=R[i+1,1];
> cont:=cont+1:
> od:
> _eq[1]:=eq[2*nh+1]-eqhbm[2*nh+1]:
> _eq[2]:=eq[2*nh+2]-eqhbm[2*nh+2]:

```

Equações que determinam os pontos fixos

```

> _eq[3]:=(u0-u0_0)^2+(v0-v0_0)^2+(Omega-Omega_0)^2-r^2;
> HH2:=Matrix([[diff(_eq[1],u0),diff(_eq[1],v0)],
> [diff(_eq[2],u0),diff(_eq[2],v0)]]):
> VV2:=Matrix([[-_eq[1]],[-_eq[2]]]):
> HH3:=Matrix(
> [[diff(_eq[1],u0),diff(_eq[1],v0),diff(_eq[1],Omega)],
> [diff(_eq[2],u0),diff(_eq[2],v0),diff(_eq[2],Omega)],
> [diff(_eq[3],u0),diff(_eq[3],v0),diff(_eq[3],Omega)]]):
> VV3:=Matrix([[-_eq[1]],[-_eq[2]],[-_eq[3]]]):
> _eq3:=(u0-u0_0)^2+(v0-v0_0)^2+(Omega-Omega_0)^2-r^2
> EXCUTE_NR:=proc(naprox)
> global HH2,VV2,u0,v0,DELTA;
> local i;
> for i from 1 to naprox do
> DELTA:=evalm(inverse(evalf(HH2))&*VV2);
> u0:=u0+evalf(DELTA[1,1]);
> v0:=v0+evalf(DELTA[2,1]);
> od:
> "residuo",evalf(DELTA[1,1]),evalf(DELTA[2,1]);
> end proc:
> EXCUTE_NR3:=proc(naprox)
> global HH3,VV3,u0,phi,Omega,DELTA,u00,phi0,Omega0,r;
> local i;
> for i from 1 to naprox do
> DELTA:=evalm(inverse(evalf(HH3))&*VV3);
> u0:=u0+evalf(DELTA[1,1]);
> phi:=phi+evalf(DELTA[2,1]);
> Omega:=Omega+evalf(DELTA[3,1]);
> od:
> "residuo",evalf(DELTA[1,1]),evalf(DELTA[2,1]),
> evalf(DELTA[3,1]);
> end proc:

```

```

> for i from 1 to 2 do
>   aux:=HH2[i,1]:
>   for j from 1 to nt do
>     aux:=subs(diff(du[j](u0,v0,Omega),u0)=duu0[j],aux);
>   od:
>   HH2[i,1]:=subs({seq(du[ii](u0,v0,Omega)=du[ii],
>     ii=1..nt)},aux):
>   aux:=HH2[i,2]:
>   for j from 1 to nt do
>     aux:=subs(diff(du[j](u0,v0,Omega),v0)=duv0[j],aux);
>   od:
>   HH2[i,2]:=subs({seq(du[ii](u0,v0,Omega)=du[ii],
>     ii=1..nt)},aux):
>   VV2[i,1]:=subs({seq(du[ii](u0,v0,Omega)=du[ii],ii=1..nt)
> },VV2[i,1]):
>   od:
>   for i from 1 to 3 do
>     aux:=HH3[i,1]:
>     for j from 1 to nt do
>       aux:=subs(diff(du[j](u0,v0,Omega),u0)=duu0[j],aux);
>     od:
>     HH3[i,1]:=subs({seq(du[ii](u0,v0,Omega)=du[ii],
>       ii=1..nt)},aux):
>     aux:=HH3[i,2]:
>     for j from 1 to nt do
>       aux:=subs(diff(du[j](u0,v0,Omega),v0)=duv0[j],aux);
>     od:
>     HH3[i,2]:=subs({seq(du[ii](u0,v0,Omega)=du[ii],
>       ii=1..nt)},aux):
>     aux:=HH3[i,3]:
>     for j from 1 to nt do
>       aux:=subs(diff(du[j](u0,v0,Omega),Omega)=duomega[j],aux);
>     od:
>     HH3[i,3]:=subs({seq(du[ii](u0,v0,Omega)=du[ii],
>       ii=1..nt)},aux):
>     VV3[i,1]:=subs({seq(du[ii](u0,v0,Omega)=du[ii],ii=1..nt)
> },VV3[i,1]):
>   od:

```

Remontagem do problema

```

> unassign('cc'); unassign('dd');
> unassign('du'); unassign('duu0'); unassign('duv0');
> unassign('ccu0'); unassign('ccv0');
> unassign('ddu0'); unassign('ddv0');
> unassign('ccu0u0'); unassign('ccu0v0');
> unassign('ccv0u0'); unassign('ccv0v0');
> unassign('ddu0u0'); unassign('ddu0v0');
> unassign('ddv0u0'); unassign('ddv0v0');
> omega0:='omega0': beta:='beta': delta:= 'delta': F:='F':
> zeta:='zeta': F0:='F0': Omega:='Omega':
> b:='b': u0:='u0': phi:='phi': v0:='v0':
> xx2;

```

```

cc1(u0, v0, Ω) cos(Ω t) + dd1(u0, v0, Ω) sin(Ω t)
+ cc2(u0, v0, Ω) cos(3 Ω t) + dd2(u0, v0, Ω) sin(3 Ω t)
> xx2:=subs(
> {seq(cc[jj](u0,v0,0mega)=cc[jj],jj=0..nt),
> seq(dd[jj](u0,v0,0mega)=dd[jj],jj=1..nt)},xx2);
xx2 := cc1 cos(Ω t) + dd1 sin(Ω t) + cc2 cos(3 Ω t) + dd2 sin(3 Ω t)

```

solução

```

> CC[0]:=subs({seq(du[jj](u0,v0,0mega)=du[jj],
> jj=1..nt)},A[0]);
> for i from 1 to nh do;
> CC[i]:=subs({seq(du[jj](u0,v0,0mega)=du[jj],
> jj=1..nt)},A[i]);
> DD[i]:=subs({seq(du[jj](u0,v0,0mega)=du[jj],
> jj=1..nt)},B[i]);
> od:
> c0[0];

```

$$u0$$

```

> c0[2];

```

$$F - 2\zeta\omega_0 v0 - \omega_0^2 u0 - \beta u0^3$$

```

> c0[5];

```

$$\begin{aligned}
& -2\zeta\omega_0 du_4(u0, v0, \Omega) - \omega_0^2 du_3(u0, v0, \Omega) - 6\beta v0^3 \\
& - 18\beta u0 v0 du_2(u0, v0, \Omega) - 3\beta u0^2 du_3(u0, v0, \Omega)
\end{aligned}$$

derivadas fundamentais

```

> DU[0]:=u0;
> DU[1]:=v0;
> for i from 2 to nt do;
> DU[i]:=expand(subs({seq(du[jj](u0,v0,0mega)=du[jj],
jj=2..i-1)},c0[i]));
> od:

```

$$DU_0 := u0$$

$$DU_1 := v0$$

```

> DU[2];
> DU[3];
> DU[4];
> DU[5];

```

$$\begin{aligned}
& F - 2\zeta\omega_0 v0 - \omega_0^2 u0 - \beta u0^3 \\
& - 2\zeta\omega_0 du_2 - \omega_0^2 v0 - 3\beta u0^2 v0 \\
& - F\Omega^2 - 2\zeta\omega_0 du_3 - \omega_0^2 du_2 - 6\beta u0 v0^2 - 3\beta u0^2 du_2 \\
& - 2\zeta\omega_0 du_4 - \omega_0^2 du_3 - 6\beta v0^3 - 18\beta u0 v0 du_2 - 3\beta u0^2 du_3
\end{aligned}$$

derivadas das derivadas fundamentais

```

> for i from 0 to 2 do;
> DUu0[i]:=diff(DU[i],u0);
> DUv0[i]:=diff(DU[i],v0);
> DUomega[i]:=diff(DU[i],0mega);
> od:
> for i from 3 to nt do;
> DUu0[i]:=subs({seq(diff(du[jj](u0,v0,0mega),u0)=duu0[jj],
jj=2..i),

```

```

> seq(du[jj](u0,v0,Omega)=du[jj],jj=2..i)}, diff(c0[i],u0));
> DUv0[i]:=subs({seq(diff(du[jj](u0,v0,Omega),v0)=duv0[jj],
jj=2..i)},
> seq(du[jj](u0,v0,Omega)=du[jj],jj=2..i)}, diff(c0[i],v0));
> DUomega[i]:=subs({seq(diff(du[jj](u0,v0,Omega),Omega)
= duomega[jj],jj=2..i)}, seq(du[jj](u0,v0,Omega)=du[jj],
jj=2..i)}, diff(c0[i],Omega));
> od:

```

Rotinas

```

> COMPUTE_TRUE_DU:=proc()
> global zeta,omega0,beta,F0,F,Omega,u0,v0,nt,du,DU,true_du;
> local i,j;
> true_du[0]:=DU[0];
> true_du[1]:=DU[1];
> true_du[2]:=DU[2];
> for i from 3 to nt do
> true_du[i]:=expand(subs({seq(du[j]=true_du[j],j=2..i-1)},
DU[i]));
> od;
> "ok";
> end proc:
> COMPUTE_TRUE_DDU:=proc()
> global zeta,omega0,beta,F0,F,Omega,u0,v0,nt,
> duu0,duv0,du,DUu0,DUv0,
> DUomega,DU,true_du,true_duu0,true_duv0,true_duomega;
> local i,j;
> true_duu0[0]:=DUu0[0]; true_duv0[0]:=DUv0[0];
> true_duomega[0]:=DUomega[0];
> true_duu0[1]:=DUu0[1]; true_duv0[1]:=DUv0[1];
> true_duomega[1]:=DUomega[1];
> true_duu0[2]:=DUu0[2]; true_duv0[2]:=DUv0[2];
> true_duomega[2]:=DUomega[2];
> for i from 3 to nt do
> true_duu0[i]:=expand(subs({seq(du[j]=true_du[j],j=2..i-1),
> seq(duu0[j]=true_duu0[j],j=2..i-1)}, DUu0[i]));
> true_duv0[i]:=expand(subs({seq(du[j]=true_du[j],j=2..i-1),
> seq(duv0[j]=true_duv0[j],j=2..i-1)}, DUv0[i]));
> true_duomega[i]:=expand(subs({seq(du[j]=true_du[j],
j=2..i-1),
> seq(duomega[j]=true_duomega[j],j=2..i-1)}, DUomega[i]));
> od;
> "ok";
> end proc:
> COMPUTE_TRUE_VV:=proc()
> global zeta,omega0,beta,F0,F,Omega,u0,v0,nt,duu0,duv0,du,
> true_du,true_duu0,true_duv0,true_vv,VV2;
> local i;
> true_vv:=Matrix(2,1):
> for i from 1 to 2 do
> true_vv[i,1]:=subs({seq(du[j]=true_du[j],j=2..nt)},
VV2[i,1]);

```

```

> od:
> "ok";
> end proc:
> COMPUTE_TRUE_VV3:=proc()
> global zeta,omega0,beta,F0,F,Omega,u0,v0,nt,
> duu0,duv0,du,true_du,
> true_duu0,true_duv0,true_vv3,VV3;
> local i;
> true_vv3:=Matrix(3,1):
> for i from 1 to 2 do
> true_vv3[i,1]:=subs({seq(du[j]=true_du[j],j=2..nt)},
VV3[i,1]);
> od:
> true_vv3[3,1]:=VV3[3,1]:
> "ok";
> end proc:
> COMPUTE_TRUE_HH:=proc()
> global zeta,omega0,beta,F0,F,Omega,u0,v0,
> Omega_0,u0_0,v0_0,r,nt,
> duu0,duv0,du,true_du,true_duu0,true_duv0,true_hh,HH2;
> local i;
> true_hh:=Matrix(2):
> for i from 1 to 2 do
> true_hh[i,1]:=subs({seq(du[j]=true_du[j],j=2..nt),
> seq(duu0[j]=true_duu0[j],j=2..nt)},HH2[i,1]);
> od:
> for i from 1 to 2 do
> true_hh[i,2]:=subs({seq(du[j]=true_du[j],j=2..nt),
> seq(duv0[j]=true_duv0[j],j=2..nt)},HH2[i,2]);
> od:
> "ok";
> end proc:
> COMPUTE_TRUE_HH3:=proc()
> global zeta,omega0,beta,F0,F,Omega,u0,v0,
> Omega_0,u0_0,v0_0,r,nt,
> duu0,duv0,du,true_du,true_duu0,true_duv0,true_hh3,HH3;
> local i;
> true_hh3:=Matrix(3):
> for i from 1 to 2 do
> true_hh3[i,1]:=subs({seq(du[j]=true_du[j],j=2..nt),
> seq(duu0[j]=true_duu0[j],j=2..nt)},HH3[i,1]);
> od:
> for i from 1 to 2 do
> true_hh3[i,2]:=subs({seq(du[j]=true_du[j],j=2..nt),
> seq(duv0[j]=true_duv0[j],j=2..nt)},HH3[i,2]);
> od:
> for i from 1 to 2 do
> true_hh3[i,3]:=subs({seq(du[j]=true_du[j],j=2..nt),
> seq(duomega[j]=true_duomega[j],j=2..nt)},HH3[i,3]);
> od:
> true_hh3[3,1]:=HH3[3,1]: true_hh3[3,2]:=HH3[3,2]:
> true_hh3[3,3]:=HH3[3,3]:
> "ok";
> end proc:

```

```

> COMPUTE_ONE_STEP:=proc()
> global true_hh,true_vv,u0,v0,COMPUTE_TRUE_DU,
> COMPUTE_TRUE_VV,COMPUTE_TRUE_DDU,COMPUTE_TRUE_HH;
> COMPUTE_TRUE_DU();
> COMPUTE_TRUE_VV();
> COMPUTE_TRUE_DDU();
> COMPUTE_TRUE_HH();
> evalm(inverse(true_hh)*true_vv);
> u0:=u0+%[1,1];
> v0:=v0+%[2,1];
> evalf(%%[1,1]),evalf(%%[2,1]);
> end proc:
> COMPUTE_ONE_AUTOMATIC_STEP:=proc()
> global
> true_hh3,true_vv3,u0,v0,Omega,COMPUTE_TRUE_DU,
> COMPUTE_TRUE_VV3,COMPUTE_TRUE_DDU,COMPUTE_TRUE_HH3;
> local aux;
> COMPUTE_TRUE_DU();
> COMPUTE_TRUE_VV3();
> COMPUTE_TRUE_DDU();
> COMPUTE_TRUE_HH3();
> aux:=evalm(inverse(true_hh3)*true_vv3);
> u0:=u0+%[1,1];
> v0:=v0+%[2,1];
> Omega:=Omega+%%[3,1];
> evalf(aux[1,1]),evalf(aux[2,1]),evalf(aux[3,1]);
> end proc:
> COMPUTE_TRUE_SOLUTION:=proc()
> global zeta,omega0,beta,F0,F,Omega,u0,v0,nt,nh,du,cc,dd,
> true_du,true_cc,true_dd,true_xx;
> local i,j;
> true_du[0]:=DU[0];
> true_du[1]:=DU[1];
> true_du[2]:=DU[2];
> true_cc[0]:=0;
> for i from 1 to nh do
> true_cc[i]:=expand(subs({seq(du[j]=true_du[j],
> j=2..nt)},CC[i]));
> true_dd[i]:=expand(subs({seq(du[j]=true_du[j],
> j=2..nt)},DD[i]));
> od;
> i:='i':
> true_xx:=true_cc[0]+sum(true_cc[i]*cos((2*i-1)*Omega*t)+
> true_dd[i]*sin((2*i-1)*Omega*t),i=1..nh);
> end proc:

```

C.1.2 Exemplo

```

> t:='t':

```



```

> eqd;
      
$$\left(\frac{d^2}{dt^2} u(t)\right) + 2\zeta\omega_0\left(\frac{d}{dt} u(t)\right) + \omega_0^2 u(t) + \beta u(t)^3 = F \cos(\Omega t)$$

> zeta:=0.05; omega0:=1; alpha:=0; beta:=1;
> F:=1; Omega:=2;

      
$$\zeta := 0.05$$

      
$$\omega_0 := 1$$

      
$$\alpha := 0$$

      
$$\beta := 1$$

      
$$F := 1$$

      
$$\Omega := 2$$


> eqd;
      
$$\left(\frac{d^2}{dt^2} u(t)\right) + 0.10\left(\frac{d}{dt} u(t)\right) + u(t) + u(t)^3 = \cos(2t)$$

Chute inicial para as coordenadas do ponto fixo da solução periódica
> u0:=1.2;
> v0:=0.2;

      
$$u0 := 1.2$$

      
$$v0 := 0.2$$


> for i from 1 to 15 do
> COMPUTE_ONE_STEP();
> od:
> COMPUTE_ONE_STEP();
> u0,v0;

      
$$0.1673185730 \cdot 10^{-11}, 0.1835355378 \cdot 10^{-9}$$

      
$$-1.933790430, 0.09771591379$$


> u0,v0;

      
$$-1.933790430, 0.09771591379$$


> XX:=COMPUTE_TRUE_SOLUTION();

      
$$XX := -1.858154359 \cos(2t) + 0.02044165762 \sin(2t)$$

      
$$-0.0756360712 \cos(6t) + 0.009472099763 \sin(6t)$$


```

Verificação da solução: integração numérica

```

> t:='t':
> eqd;

      
$$\left(\frac{d^2}{dt^2} u(t)\right) + 0.10\left(\frac{d}{dt} u(t)\right) + u(t) + u(t)^3 = \cos(2t)$$

> eqd2:=y(t)=diff(x(t),t),diff(y(t),t)=F*cos(Omega*t)
-2*omega0*zeta*dif
> f(x(t),t)
> +alpha*x(t)^2-omega0^2*x(t)-beta*x(t)^3;
> init:=x(0)=u0,y(0)=v0;

      
$$eqd2 := y(t) = \frac{d}{dt} x(t), \frac{d}{dt} y(t) = \cos(2t) - 0.10\left(\frac{d}{dt} x(t)\right) - x(t) - x(t)^3$$

      
$$init := x(0) = -1.933790430, y(0) = 0.09771591379$$

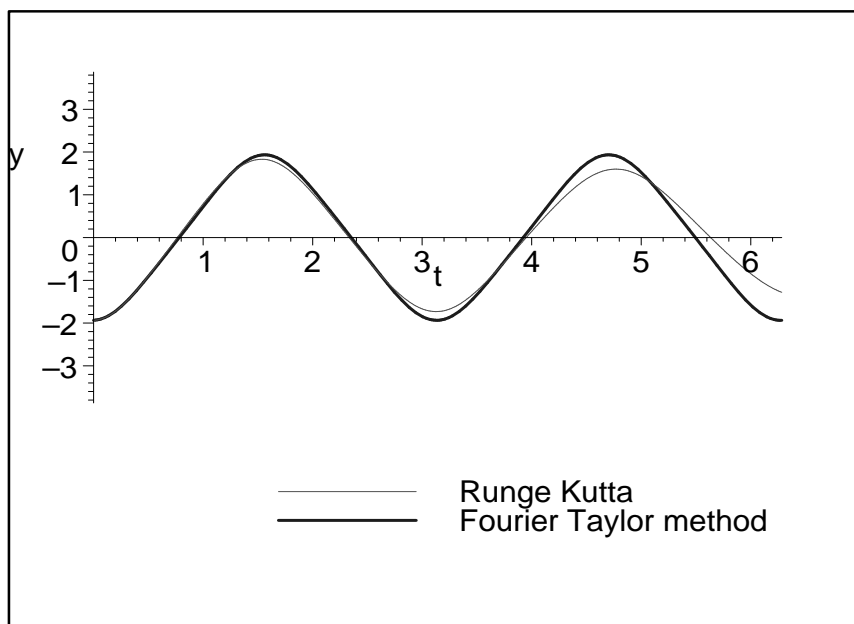

> f:=dsolve({eqd2,init
> },type=numeric,method=classical[rk4],maxfun=999999,
output=procedurelist):

```

```

> T:=evalf(2*Pi/Omega);
      T := 3.141592654
> vi:=0; vf:=evalf(2*T);
> #escrevendo na lista
> delta:=evalf(T/200): cont:=0:
> for k from vi by delta to vf do
>   cont:=cont+1;
>   od: cont;
>   dd1:=array(1..cont,1..2): dd2:=array(1..cont,1..2):
>   cont:=0:
>   for k from vi by delta to vf do
>     cont:=cont+1;
>     dd1[cont,1]:=k;
>     dd1[cont,2]:=eval(x(t),f(k));
>     dd2[cont,1]:=k;
>     dd2[cont,2]:=eval(y(t),f(k));
>   od:
>   d1g:=convert(dd1,listlist):
>   d2g:=convert(dd2,listlist):
      vi := 0
      vf := 6.283185308
      401
> plot([d1g,XX],t=0..vf,y=-2*u0..2*u0,color=[red,blue],
thickness=[2,4],legend=["Runge Kutta","Fourier Taylor
method"]);

```



C.2

Exportação de arquivo para programa em C++

```

> with(CodeGeneration):
> omega0:='omega0': beta:='beta': delta:= 'delta': F:='F':
> zeta:='zeta': F0:='F0': Omega:='Omega':
> b:='b': u0:='u0': phi:='phi': v0:='v0': x0:='x0':
> declarations:=[c::numeric, d::numeric, omega0::numeric,
> beta::numeric, Omega::numeric, F::numeric, t::numeric,
> u0::numeric, phi::numeric, u00::numeric, phi0::numeric,
> Omega0::numeric,
> du::numeric, duu0::numeric, duv0::numeric,
> duomega::numeric,
> cc::numeric, dd::numeric]:
> for i from 2 to nt do
>   for k from 1 to 1 do
>     nomes:=sprintf("duII%dJJ",i-1);
>     du_toC[i]:=C(DU[i],resultname=nomes,declare=declarations,
precision=double,output=string,optimize=false):
>   od:
>   evalf(100*i/nt);
>   od:
>   for i from 2 to nt do
>     for k from 1 to 1 do
>       nomes:=sprintf("duu0II%dJJ",i-1);
>       duu0_toC[i]:=C(DUu0[i],resultname=nomes,
>       declare=declarations,precision=double,output=string,
optimize=false):
>       nomes:=sprintf("duv0II%dJJ",i-1);
>       duv0_toC[i]:=C(DUv0[i],resultname=nomes,
>       declare=declarations, precision=double,output=string,
optimize=false):
>       nomes:=sprintf("duomegaII%dJJ",i-1);
>       duomega_toC[i]:=C(DUomega[i],resultname=nomes,
>       declare=declarations, precision=double,output=string,
optimize=false):
>     od:
>     evalf(100*i/nt);
>     od:
>     for i from 1 to 3 do
>       for k from 1 to 1 do
>         nomes:=sprintf("vII%dJJ",i-1);
>         v_toC[i]:=C(VV3[i,1],resultname=nomes,
>         declare=declarations,precision=double,output=string,
optimize=true):
>       for j from 1 to 3 do
>         nomes:=sprintf("hII%dJJII%dJJ",i-1,j-1);
>         m_toC[i,j]:=C(HH3[i,j],resultname=nomes,
>         declare=declarations,precision=double,output=string,
optimize=true):
>       od:
>     od:
>     evalf(100*i/3);
>   od:

```

```

> for i from 1 to nh do
> for k from 1 to 1 do
> nomes:=sprintf("cII%dJJ",i-1);
> ci_toC[i]:=C(CC[i],resultname=nomes,
> declare=declarations,precision=double,output=string,
optimize=false):
> nomes:=sprintf("dII%dJJ",i-1);
> di_toC[i]:=C(DD[i],resultname=nomes,
> declare=declarations,precision=double,output=string,
optimize=false):
> od:
> evalf(100*i/nh);
> od:
> xx2;
      
$$cc_1 \cos(\Omega t) + dd_1 \sin(\Omega t) + cc_2 \cos(3\Omega t) + dd_2 \sin(3\Omega t)$$

> subs(t=0,xx2):
> dx0[0]:=%;
> x0:=%:
> for i from 1 to nt do
> subs(t=0,evalf(diff(xx2/(2*nh-1)^i,t$i))):
> dx0[i]:=collect(%,Omega);
> od:
      
$$dx0_0 := cc_1 + cc_2$$

> x0;
      
$$cc_1 + cc_2$$

> nomes:=sprintf("x0",i-1):
> x0_toC:=C(x0,resultname=nomes,
> declare=declarations,precision=double,output=string,
optimize=false):
> for i from 0 to nt do
> for k from 1 to 1 do
> nomes:=sprintf("dx0II%dJJ",i);
> dx0_toC[i]:=C(dx0[i],resultname=nomes,
> declare=declarations,precision=double,output=string,
optimize=false):
> od:
> evalf(100*i/nt);
> od:

```

C.2.1

Escreve o arquivo

```

> classname:="FTMapleForced_nt";
      
$$classname := \text{"FTMapleForced\_nt"}$$


```

```

> PRINT_HEADING := proc(fd)
> fprintf(fd,"//equações from Maple\n"):
> fprintf(fd,"\n"):
> fprintf(fd,"#include <math.h>\n"):
> fprintf(fd,"#include \"ftmaple.h\"\n"):
> fprintf(fd,"\n"):
> end proc:
> PRINT_LOCAL_VARS := proc(fd)
> local cont,i,j;
> fprintf(fd,"//local vars\n"):
> cont:=0:
> for i from 1 to 10*nh do
> cont:=cont+1:
> fprintf(fd,"static double t%d",cont):
> for j from 1 to nt do
> cont:=cont+1:
> fprintf(fd,",t%d",cont):
> od:
> fprintf(fd,";\n"):
> od:
> fprintf(fd,"\n\n"):
> end proc:
> PRINT_COMPUTE_DU := proc(fd) global ci_toC,di_toC; local
i;
> fprintf(fd,"void %s%d::ComputeDU()\n",classname,nh):
> fprintf(fd,"{\n"):
> for i from 2 to nt do
> fprintf(fd,"%s",du_toC[i]):
> od:
> fprintf(fd,"}\n"):
> end proc:
> PRINT_COMPUTE_DDU := proc(fd) global ci_toC,di_toC; local
i;
> fprintf(fd,"void %s%d::ComputeDDU()\n",classname,nh):
> fprintf(fd,"{\n"):
> for i from 2 to nt do
> fprintf(fd,"%s",duu0_toC[i]):
> fprintf(fd,"%s",duv0_toC[i]):
> fprintf(fd,"%s",duomega_toC[i]):
> od:
> fprintf(fd,"}\n"):
> end proc:
> PRINT_CONSTRUCTOR := proc(fd)
> fprintf(fd,"%s%d::~%s%d()\n",classname,nh,classname,nh):
> fprintf(fd,"{\n"):
> fprintf(fd,"}\n"):
> fprintf(fd,"\n"):
> fprintf(fd,"%s%d::~~%s%d()\n",classname,nh,classname,nh):
> fprintf(fd,"{\n"):
> fprintf(fd,"}\n"):
> fprintf(fd,"\n"):
> end proc:

```

```

> PRINT_SOLUTION := proc(fd) global ci_toC, di_toC; local i;
> fprintf(fd, "void %s%d::Solution()\n", classname, nh);
> fprintf(fd, "{\n");
> for i from 1 to nh do
>   fprintf(fd, "%s", ci_toC[i]):
>   fprintf(fd, "%s", di_toC[i]):
> od:
> fprintf(fd, "}\n");
> end proc:
> PRINT_EQ := proc(fd) global m_toC, v_toC; local i, j, k;
> fprintf(fd, "void %s%d::Eq()\n", classname, nh);
> fprintf(fd, "{\n");
> fprintf(fd, "ComputeDU();\n");
> fprintf(fd, "ComputeDDU();\n");
> for i from 1 to 3 do
>   fprintf(fd, "%s", v_toC[i]):
> od:
> for i from 1 to 3 do
>   for j from 1 to 3 do
>     fprintf(fd, "%s", m_toC[i, j]):
>   od:
> od:
> fprintf(fd, "}\n");
> fprintf(fd, "\n");
> end proc:
> PRINT_COMPUTE_DX0 := proc(fd) global x0_toC, dx0_toC; local
i;
> fprintf(fd, "void %s%d::ComputedX0()\n", classname, nh);
> fprintf(fd, "{\n");
> fprintf(fd, "%s", x0_toC):
> for i from 0 to nt do
>   fprintf(fd, "%s", dx0_toC[i]):
> od:
> fprintf(fd, "for(int i=0; i<nh; ++i)\n");
> fprintf(fd, " dx0[i] *= pow(2*nh-1, i);\n");
> fprintf(fd, "}\n");
> end proc:
> fname:=sprintf("c:\\ftmaple_n13_nt=%d.cpp", nh);
      fname := "c:\\ftmaple_n13_nt=2.cpp"

```

writing...

```

> fname;
> fd:=fopen(fname, WRITE, BINARY);
> PRINT_HEADING(fd);
> PRINT_LOCAL_VARS(fd);
> PRINT_SOLUTION(fd);
> PRINT_COMPUTE_DX0(fd);
> PRINT_COMPUTE_DU(fd);
> PRINT_COMPUTE_DDU(fd);
> PRINT_EQ(fd);
> fclose(fd);
      "c:\\ftmaple_n13_nt=2.cpp"
      fd := 0

```

2
2
2
2
2
1

C.2.2

Arquivo exportado

```
//equações from Maple
#include <math.h>
#include "ftmaple.h"
//local vars
static double t1,t2,t3,t4,t5,t6,t7,t8;
static double t9,t10,t11,t12,t13,t14,t15,t16;
static double t17,t18,t19,t20,t21,t22,t23,t24;
static double t25,t26,t27,t28,t29,t30,t31,t32;
static double t33,t34,t35,t36,t37,t38,t39,t40;
static double t41,t42,t43,t44,t45,t46,t47,t48;

void FTMapleForced_nt2::Solution()
{
c[0]=0.9e1/0.8e1 * u0 - pow(Omega, - 0.2e1) * ( - F/0.2e1 + zeta * omega0 *
v0 + omega0 * omega0 * u0/0.2e1 + beta * pow(u0,0.3e1)/0.2e1)/0.4e1;
d[0]=0.9e1/0.8e1/Omega * v0 - 0.3e1/0.4e1 * pow(Omega, - 0.3e1) * (zeta
* omega0 * du[1]/0.3e1 + omega0 * omega0 * v0/0.6e1 + beta * u0 * u0 *
v0/0.2e1);
c[1]= - u0/0.8e1 + pow(Omega, - 0.2e1) * ( - F/0.2e1 + zeta * omega0 * v0
+ omega0 * omega0 * u0/0.2e1 + beta * pow(u0,0.3e1)/0.2e1)/0.4e1;
d[1]= - 0.1e1/Omega * v0/0.24e2 + pow(Omega, - 0.3e1) * (zeta * omega0 *
du[1]/0.3e1 + omega0 * omega0 * v0/0.6e1 + beta * u0 * u0 * v0/0.2e1)/0.4e1;
}

void FTMapleForced_nt2::ComputeDX0()
{
x0=cc[0] + cc[1];
dx0[0]=cc[0] + cc[1];
dx0[1]=(0.3333333333e0 * dd[0] + 0.1e1 * dd[1]) * Omega;
dx0[2]=( - 0.1111111111e0 * cc[0] - 0.1e1 * cc[1]) * Omega * Omega;
dx0[3]=( - 0.3703703704e - 1 * dd[0] - 0.1e1 * dd[1]) * pow(Omega,0.3e1);
dx0[4]=(0.1234567901e - 1 * cc[0] + 0.1e1 * cc[1]) * pow(Omega,0.4e1);
dx0[5]=(0.4115226337e - 2 * dd[0] + 0.1e1 * dd[1]) * pow(Omega,0.5e1);
dx0[6]=( - 0.1371742112e - 2 * cc[0] - 0.1e1 * cc[1]) * pow(Omega,0.6e1);
dx0[7]=( - 0.4572473708e - 3 * dd[0] - 0.1e1 * dd[1]) * pow(Omega,0.7e1);
for(int i=0; i<nh; ++i)
```

```
dx0[i] * =pow(2 * nh - 1,i);
}
```

```
void FTMapleForced_nt2::ComputeDU()
{
du[1]=F - 0.2e1 * zeta * omega0 * v0 - omega0 * omega0 * u0 - beta *
pow(u0,0.3e1);
du[2]= - 0.2e1 * zeta * omega0 * du[1] - omega0 * omega0 * v0 - 0.3e1 * beta
* u0 * u0 * v0;
du[3]= - F * Omega * Omega - 0.2e1 * zeta * omega0 * du[2] - omega0 *
omega0 * du[1] - 0.6e1 * beta * u0 * v0 * v0 - 0.3e1 * beta * u0 * u0 * du[1];
du[4]= - 0.2e1 * zeta * omega0 * du[3] - omega0 * omega0 * du[2] - 0.6e1 *
beta * pow(v0,0.3e1) - 0.18e2 * beta * u0 * v0 * du[1] - 0.3e1 * beta * u0 *
u0 * du[2];
du[5]=F * pow(Omega,0.4e1) - 0.2e1 * zeta * omega0 * du[4] - omega0 *
omega0 * du[3] - 0.36e2 * beta * v0 * v0 * du[1] - 0.18e2 * beta * u0 *
pow(du[1],0.2e1) - 0.24e2 * beta * u0 * v0 * du[2] - 0.3e1 * beta * u0 * u0 *
du[3];
du[6]= - 0.2e1 * zeta * omega0 * du[5] - omega0 * omega0 * du[4] - 0.90e2 *
beta * v0 * pow(du[1],0.2e1) - 0.60e2 * beta * v0 * v0 * du[2] - 0.60e2 * beta
* u0 * du[1] * du[2] - 0.30e2 * beta * u0 * v0 * du[3] - 0.3e1 * beta * u0 * u0
* du[4];
}
```

```
void FTMapleForced_nt2::ComputeDDU()
{
duu0[1]= - omega0 * omega0 - 0.3e1 * beta * u0 * u0;
duv0[1]= - 0.2e1 * zeta * omega0;
duomega[1]=0;
duu0[2]= - 0.2e1 * zeta * omega0 * duu0[1] - 0.6e1 * beta * u0 * v0;
duv0[2]= - 0.2e1 * zeta * omega0 * duv0[1] - omega0 * omega0 - 0.3e1 * beta
* u0 * u0;
duomega[2]= - 0.2e1 * zeta * omega0 * duomega[1];
duu0[3]= - 0.2e1 * zeta * omega0 * duu0[2] - omega0 * omega0 * duu0[1] -
0.6e1 * beta * v0 * v0 - 0.6e1 * beta * u0 * du[1] - 0.3e1 * beta * u0 * u0 *
duu0[1];
duv0[3]= - 0.2e1 * zeta * omega0 * duv0[2] - omega0 * omega0 * duv0[1] -
0.12e2 * beta * u0 * v0 - 0.3e1 * beta * u0 * u0 * duv0[1];
duomega[3]= - 0.2e1 * F * Omega - 0.2e1 * zeta * omega0 * duomega[2] -
omega0 * omega0 * duomega[1] - 0.3e1 * beta * u0 * u0 * duomega[1];
duu0[4]= - 0.2e1 * zeta * omega0 * duu0[3] - omega0 * omega0 * duu0[2] -
0.18e2 * beta * v0 * du[1] - 0.18e2 * beta * u0 * v0 * duu0[1] - 0.6e1 * beta *
u0 * du[2] - 0.3e1 * beta * u0 * u0 * duu0[2];
duv0[4]= - 0.2e1 * zeta * omega0 * duv0[3] - omega0 * omega0 * duv0[2] -
0.18e2 * beta * v0 * v0 - 0.18e2 * beta * u0 * du[1] - 0.18e2 * beta * u0 * v0
* duv0[1] - 0.3e1 * beta * u0 * u0 * duv0[2];
duomega[4]= - 0.2e1 * zeta * omega0 * duomega[3] - omega0 * omega0 *
duomega[2] - 0.18e2 * beta * u0 * v0 * duomega[1] - 0.3e1 * beta * u0 * u0 *
```



```

duomega[2];
duu0[5]= - 0.2e1 * zeta * omega0 * duu0[4] - omega0 * omega0 * duu0[3] -
0.36e2 * beta * v0 * v0 * duu0[1] - 0.18e2 * beta * pow(du[1],0.2e1) - 0.36e2
* beta * u0 * du[1] * duu0[1] - 0.24e2 * beta * v0 * du[2] - 0.24e2 * beta * u0
* v0 * duu0[2] - 0.6e1 * beta * u0 * du[3] - 0.3e1 * beta * u0 * u0 * duu0[3];
duv0[5]= - 0.2e1 * zeta * omega0 * duv0[4] - omega0 * omega0 * duv0[3] -
0.72e2 * beta * v0 * du[1] - 0.36e2 * beta * v0 * v0 * duv0[1] - 0.36e2 * beta
* u0 * du[1] * duv0[1] - 0.24e2 * beta * u0 * du[2] - 0.24e2 * beta * u0 * v0 *
duv0[2] - 0.3e1 * beta * u0 * u0 * duv0[3];
duomega[5]=0.4e1 * F * pow(Omega,0.3e1) - 0.2e1 * zeta * omega0 *
duomega[4] - omega0 * omega0 * duomega[3] - 0.36e2 * beta * v0 * v0 *
duomega[1] - 0.36e2 * beta * u0 * du[1] * duomega[1] - 0.24e2 * beta * u0 *
v0 * duomega[2] - 0.3e1 * beta * u0 * u0 * duomega[3];
duu0[6]= - 0.2e1 * zeta * omega0 * duu0[5] - omega0 * omega0 * duu0[4] -
0.180e3 * beta * v0 * du[1] * duu0[1] - 0.60e2 * beta * v0 * v0 * duu0[2] -
0.60e2 * beta * du[1] * du[2] - 0.60e2 * beta * u0 * duu0[1] * du[2] - 0.60e2 *
beta * u0 * du[1] * duu0[2] - 0.30e2 * beta * v0 * du[3] - 0.30e2 * beta * u0 *
v0 * duu0[3] - 0.6e1 * beta * u0 * du[4] - 0.3e1 * beta * u0 * u0 * duu0[4];
duv0[6]= - 0.2e1 * zeta * omega0 * duv0[5] - omega0 * omega0 * duv0[4] -
0.90e2 * beta * pow(du[1],0.2e1) - 0.180e3 * beta * v0 * du[1] * duv0[1] -
0.120e3 * beta * v0 * du[2] - 0.60e2 * beta * v0 * v0 * duv0[2] - 0.60e2 * beta
* u0 * duv0[1] * du[2] - 0.60e2 * beta * u0 * du[1] * duv0[2] - 0.30e2 * beta
* u0 * du[3] - 0.30e2 * beta * u0 * v0 * duv0[3] - 0.3e1 * beta * u0 * u0 *
duv0[4];
duomega[6]= - 0.2e1 * zeta * omega0 * duomega[5] - omega0 * omega0 *
duomega[4] - 0.180e3 * beta * v0 * du[1] * duomega[1] - 0.60e2 * beta * v0 *
v0 * duomega[2] - 0.60e2 * beta * u0 * duomega[1] * du[2] - 0.60e2 * beta *
u0 * du[1] * duomega[2] - 0.30e2 * beta * u0 * v0 * duomega[3] - 0.3e1 * beta
* u0 * u0 * duomega[4];
}

```

```

void FTMapleForced_nt2::Eq()
{
ComputeDU();
ComputeDDU();
t1=Omega * Omega;
t4=zeta * omega0;
t8=omega0 * omega0;
t9=du[1];
t13=v0 * v0;
t16=u0 * u0;
t31=0.1e1/t1 * ( - F/0.2e1 + t4 * v0 + t8 * u0/0.2e1 + beta * t16 *
u0/0.2e1)/0.4e1;
t33=t1 * t1;
v[0]=F * t1/0.24e2 + t4 * du[2]/0.12e2 + t8 * t9/0.24e2 + beta * u0 *
t13/0.4e1 + beta * t16 * t9/0.8e1 + (0.9e1/0.8e1 * u0 - t31) * t33/0.24e2 +
0.27e2/0.8e1 * ( - u0/0.8e1 + t31) * t33;
t1=zeta * omega0;

```

```

t5=omega0 * omega0;
t6=du[2];
t9=v0 * v0;
t14=du[1];
t18=u0 * u0;
t19=beta * t18;
t23=0.1e1/Omega * v0;
t25=Omega * Omega;
t35=0.1e1/t25/Omega * (t1 * t14/0.3e1 + t5 * v0/0.6e1 + t19 * v0/0.2e1);
t38=t25 * t25;
t39=t38 * Omega;
v[1]=t1 * du[3]/0.60e2 + t5 * t6/0.120e3 + beta * t9 * v0/0.20e2 +
0.3e1/0.20e2 * beta * u0 * v0 * t14 + t19 * t6/0.40e2 + (0.9e1/0.8e1 *
t23 - 0.3e1/0.4e1 * t35) * t39/0.120e3 + 0.81e2/0.40e2 * ( - t23/0.24e2 +
t35/0.4e1) * t39;
t2=pow(u0 - u0_0,0.2e1);
t4=pow(v0 - v0_0,0.2e1);
t6=pow(Omega - Omega_0,0.2e1);
t7=r * r;
v[2]= - t2 - t4 - t6 + t7;
t5=omega0 * omega0;
t6=duu0[1];
t9=v0 * v0;
t16=u0 * u0;
t17=beta * t16;
t20=Omega * Omega;
t26=0.1e1/t20 * (t5/0.2e1 + 0.3e1/0.2e1 * t17)/0.4e1;
t28=t20 * t20;
h[0][0]= - zeta * omega0 * duu0[2]/0.12e2 - t5 * t6/0.24e2 - beta * t9/0.4e1 -
beta * u0 * du[1]/0.4e1 - t17 * t6/0.8e1 - (0.9e1/0.8e1 - t26) * t28/0.24e2 -
0.27e2/0.8e1 * ( - 0.1e1/0.8e1 + t26) * t28;
t5=omega0 * omega0;
t6=duv0[1];
t12=u0 * u0;
t16=Omega * Omega;
h[0][1]= - zeta * omega0 * duv0[2]/0.12e2 - t5 * t6/0.24e2 - beta * u0 *
v0/0.2e1 - beta * t12 * t6/0.8e1 - 0.5e1/0.6e1 * t16 * zeta * omega0;
t3=zeta * omega0;
t7=omega0 * omega0;
t8=duomega[1];
t11=u0 * u0;
t22= - F/0.2e1 + t3 * v0 + t7 * u0/0.2e1 + beta * t11 * u0/0.2e1;
t26=Omega * Omega;
t29=0.1e1/t26 * t22/0.4e1;
t31=t26 * Omega;
h[0][2]= - F * Omega/0.12e2 - t3 * duomega[2]/0.12e2 - t7 * t8/0.24e2 - beta
* t11 * t8/0.8e1 + 0.5e1/0.3e1 * Omega * t22 - (0.9e1/0.8e1 * u0 - t29) *
t31/0.6e1 - 0.27e2/0.2e1 * ( - u0/0.8e1 + t29) * t31;

```

```

t1=zeta * omega0;
t5=omega0 * omega0;
t6=duu0[2];
t13=beta * u0;
t14=duu0[1];
t21=u0 * u0;
t25=Omega * Omega;
h[1][0]= - t1 * duu0[3]/0.60e2 - t5 * t6/0.120e3 - 0.3e1/0.20e2 * beta * v0
* du[1] - 0.3e1/0.20e2 * t13 * v0 * t14 - t13 * du[2]/0.20e2 - beta * t21 *
t6/0.40e2 - t25 * (t1 * t14/0.3e1 + t13 * v0)/0.2e1;
t1=zeta * omega0;
t5=omega0 * omega0;
t6=duv0[2];
t9=v0 * v0;
t12=beta * u0;
t16=duv0[1];
t20=u0 * u0;
t21=beta * t20;
t24=0.1e1/Omega;
t26=Omega * Omega;
t34=0.1e1/t26/Omega * (t1 * t16/0.3e1 + t5/0.6e1 + t21/0.2e1);
t37=t26 * t26;
t38=t37 * Omega;
h[1][1]= - t1 * duv0[3]/0.60e2 - t5 * t6/0.120e3 - 0.3e1/0.20e2 * beta * t9 -
0.3e1/0.20e2 * t12 * du[1] - 0.3e1/0.20e2 * t12 * v0 * t16 - t21 * t6/0.40e2
- (0.9e1/0.8e1 * t24 - 0.3e1/0.4e1 * t34) * t38/0.120e3 - 0.81e2/0.40e2 * ( -
t24/0.24e2 + t34/0.4e1) * t38;
t1=zeta * omega0;
t5=omega0 * omega0;
t6=duomega[2];
t10=duomega[1];
t14=u0 * u0;
t15=beta * t14;
t18=Omega * Omega;
t20=0.1e1/t18 * v0;
t22=t18 * t18;
t31=t1 * du[1]/0.3e1 + t5 * v0/0.6e1 + t15 * v0/0.2e1;
t32=0.1e1/t22 * t31;
t35=0.1e1/t18/Omega;
t38=t35 * zeta * omega0 * t10;
t41=Omega * t22;
t45=0.1e1/Omega * v0;
t47=t35 * t31;
h[1][2]= - t1 * duomega[3]/0.60e2 - t5 * t6/0.120e3 - 0.3e1/0.20e2 * beta
* u0 * v0 * t10 - t15 * t6/0.40e2 - ( - 0.9e1/0.8e1 * t20 + 0.9e1/0.4e1 *
t32 - t38/0.4e1) * t41/0.120e3 - (0.9e1/0.8e1 * t45 - 0.3e1/0.4e1 * t47) *
t22/0.24e2 - 0.81e2/0.40e2 * (t20/0.24e2 - 0.3e1/0.4e1 * t32 + t38/0.12e2) *
t41 - 0.81e2/0.8e1 * ( - t45/0.24e2 + t47/0.4e1) * t22;

```

```
h[2][0]=0.2e1 * u0 - (double)(2 * u0_0);  
h[2][1]=2 * v0 - 2 * v0_0;  
h[2][2]=0.2e1 * Omega - (double)(2 * Omega_0);  
}
```